Three Approaches to Ordinal Classification

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Ordinal classification consists in **predicting** a **label** taken from a **finite** and **ordered set** for an **object** described by some **attributes**.

This problem shares some characteristics of **multi-class** classification and regression, but:

- the order between class labels cannot be neglected,
- the scale of the decision attribute is not cardinal.

Recommender system predicting a rating of a movie for a given user.











???

Email filtering to ordered groups like: important, normal, later, or spam.



Nature of ordinal classification:

- Classification with ordered class labels?
- Degenerate ranking problem?

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Denotation:

- *K* number of classes
- y actual label
- \hat{y} predicted label
- x attributes
- $f(\mathbf{x})$ prediction (ranking or utility) function
- $L(\cdot)$ loss function
- $\left[\!\left[\cdot\right]\!\right]$ Boolean test

Ordinal Classification – Probability Estimation:

• Prediction risk is defined by a loss matrix:

$$\mathbf{L}(y,\hat{y}) = (l_{y,\hat{y}})_{K \times K}$$

with v-shaped rows and zeros on diagonal.

$$\mathbf{L}(y, \hat{y}) = \begin{pmatrix} 0 & 1 & 2 & 3 \\ 1 & 0 & 1 & 2 \\ 2 & 1 & 0 & 1 \\ 3 & 2 & 1 & 0 \end{pmatrix}$$

Ordinal Classification – Probability Estimation:

• Bayes decision for the loss matrix $\mathbf{L}(y, \hat{y})$ is given by:

$$\hat{y}^* = \arg\min_{\hat{y}} \sum_{k=1}^{K} \Pr(y = k | \mathbf{x}) \mathbf{L}(k, \hat{y}).$$

- To solve the problem, we need to **estimate** conditional probabilities $Pr(y = k | \mathbf{x})$ a lot of algorithms ...
- We can **decompose** the problem to K-1 binary problems by utilizing the order of labels y: the result then are estimates of $Pr(y > k | \mathbf{x}), k = 1, ..., K 1$.
- To satisfy monotonicity of $Pr(y > k | \mathbf{x})$, k = 1, ..., K 1, we use isotonic regression.
- Other possibilities allowed ...

Ordinal Classification – Probability Estimation:

• Given $\Pr(y = k | \mathbf{x})$, $k = 1, \dots, K$, the optimal prediction is:

$$\hat{y}^* = \begin{cases} \arg \max_k \Pr(y = k | \mathbf{x}), & \text{for } l_{y\hat{y}} = \llbracket y \neq \hat{y} \rrbracket, \\ \text{median}(y | \mathbf{x}), & \text{for } l_{y\hat{y}} = |y - \hat{y}|, \\ E(y | \mathbf{x}), & \text{for } l_{y\hat{y}} = (y - \hat{y})^2. \end{cases}$$

- Absolute-error loss seems to be the most natural since its Bayes decision is median that does not depend on scale of labels.
- Any function of the probability distribution can be used for object ranking.

Ordinal Classification – Degenerate Ranking:

• Prediction risk is defined by a **rank loss** computed over pairs of objects:

$$L(y_{\circ\bullet}, f(\mathbf{x}_{\circ}), f(\mathbf{x}_{\bullet})) = \llbracket y_{\circ\bullet}(f(\mathbf{x}_{\circ}) - f(\mathbf{x}_{\bullet})) \leqslant 0 \rrbracket,$$

where

$$y_{\circ\bullet} = \operatorname{sgn}(y_\circ - y_\bullet),$$

and $f(\mathbf{x})$ is a **ranking** (or **utility**) function.

 $y_{i_1} > y_{i_2} > y_{i_3} > \dots > y_{i_{N-1}} > y_{i_N}$ $f(\mathbf{x}_{i_1}) > f(\mathbf{x}_{i_3}) > f(\mathbf{x}_{i_2}) > \dots > f(\mathbf{x}_{i_{N-1}}) > f(\mathbf{x}_{i_N})$

Ordinal Classification – Degenerate Ranking:

- This approach **ranks** the objects.
- To assign class labels, one has to compute thresholds on a range of the ranking function with respect to a given loss matrix.
- Rank loss minimization is strictly connected with maximization of **AUC criterion** used in binary classification.
- Minimization of rank loss on training set has **quadratic complexity** with respect to number of object, however, in the case of K ordered classes, the algorithm can work in **linear** time.

Ordinal Classification – Threshold Loss:

• Prediction risk is defined by threshold loss:

$$L(y, f(\mathbf{x}), \boldsymbol{\theta}) = \sum_{k=1}^{K-1} \llbracket y_k(f(\mathbf{x}) - \theta_k) \ge 0 \rrbracket,$$

where $\theta = (\theta_0, \dots, \theta_K)$ are consecutive thresholds to be computed simultaneously with $f(\mathbf{x})$, and

$$y_k = 1$$
, if $y > k$, and $y_k = -1$, otherwise $y \leq k$.

$$\theta_0 = -\infty \dots \theta_1 = -3.5 \qquad \theta_2 = -1.2 \dots \theta_{k-1} = 1.2 \qquad \theta_{k-2} = 3.8 \dots \theta_K = \infty$$

Ordinal Classification – Threshold Loss:

- This approach shares characteristics of the previous two.
- Comparison of an object to thresholds instead to all other training objects – lower complexity, but linear algorithms exist for rank loss minimization in ordinal classification settings.
- Joint solution for all K 1 binary problems no need of isotonization of conditional probabilities, but the result is a single value.
- Weighted threshold loss can approximate any loss matrix.

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Boosting-like Algorithms for Three Approaches:

• Prediction function is an ensemble of decision rules:

$$f(\mathbf{x}) = \alpha_0 + \sum_{m=1}^M r_m(\mathbf{x}).$$

• We used **boosting** approach to learn $f(\mathbf{x})$: in each iteration, a single rule is generated by concentrating on examples which were hardest to classify correctly by previous rules with respect to a given **loss function**.

Boosting-like Algorithms for Three Approaches:

- Ordinal ENDER decomposes the problem into a sequence of binary problems for estimating Pr(y > k|x); uses isotonic regression for isotonization of the estimates; final prediction is median over computed class distribution.
- **RankRules** minimizes (exponential) rank loss; parameterized to minimize absolute-error.
- **ORDER** minimizes (exponential) threshold loss; parameterized to minimize absolute-error.
- ENDER-Abs reference algorithm constructing ensemble of decision rules by direct minimization of absolute-error.

All the algorithms work in **linear time** with respect to number of training example (plus log-linear time for sorting used once in preprocessing phase).

Experimental Results:

- Comparison of Ordinal ENDER, RankRules, RankRules and ENDER AE.
- 19 benchmark sets taken from Luis Torgo repository transformed from regression to ordinal classification settings.
- Average ranks are computed with repect to mean absolute error obtained on each data set.
- Critical difference in average ranks is CD = 1.076.



Experimental Results:

- There is almost **no quantitative difference** in performance and time consumption: RankRules is slightly slower.
- **Qualitative differences**: Ordinal ENDER is related to probability estimation, but RankRules to AUC maximization.
- Ensemble of decision rules are **competitive** to: RankBoost AE, ORBoost-All, SVM-IMC.









Ordinal Matrix Factorization:

• Given **sparse** matrix **Y** of observed values build a model based on **matrix factorization**:

$$\mathbf{Y} \simeq \hat{\mathbf{Y}} = \mathbf{U}\mathbf{V}^T$$

where U is an $I \times M$ and \mathbf{V}^T is a $M \times J$ matrix.

• The **prediction** is then defined by:

$$\hat{y}_{ij} = \sum_{m=1}^{M} u_{im} v_{jm}.$$

- **Example**: *I* is the number of users, *J* is the number of movies in the movie recommender system, and *M* is number of features describing users and movies.
- For learning we use **gradient descent** applied alternately to U and V matrices with respect to a given **loss function**.

Ordinal Matrix Factorization for Three Approaches:

- **Decomposition schema** for probability estimation.
- Minimization of rank loss.
- Minimization of threshold loss.
- Hypothesis: all the approaches perform similarly.
- For all three approaches **linear** algorithms exists: minimization of (exponential) rank loss, however, is the most demanding.
- No satisfactory results yet :(
- Work in progress ...





3 Ordinal Matrix Factorization



Conclusions:

- Nature of ordinal classification?
- Three approaches to ordinal classification.
- Boosting-like algorithm: rather qualitative than quantitative differences between these approaches.
- Ordinal Matrix factorization: in progress