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>>> Operating Systems And Applications For Embedded Systems  
>>> Build System
```

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```
>>> Plan
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## 1. Build system

- Open source build systems

- Abilities

- Other useful features

- Open source build systems

## 2. Buildroot

- Buildroot

- Installing

- Configuring

- Running

- License compliance

- Adding source

  - package/Config.in

  - package/hello/Config.in

  - package/hello/hello.mk

  - package/hello/src/Makefile

## 3. The Yocto Project

- Components

- Installing the Yocto Project

- Configuring

- Building

- Running

- BitBake and recipes

- Interesting features

```
>>> Open source build systems
```

- \* The toolchain
- \* The bootloader
- \* The kernel
- \* The root filesystem

>>> Abilities

- \* Download a source from upstream, either directly from the source code control system or as an archive, and cache it locally
- \* Apply patches to enable cross compilation, fix architecture-dependent bugs, apply local configuration policies, and so on
- \* Build the various components
- \* Create a staging area and assemble a root filesystem
- \* Create image files in various formats ready to be loaded onto the target

```
>>> Other useful features
```

- \* Add your own packages containing, for example, applications or kernel changes
- \* Select various root filesystem profiles: large or small, with and without graphics or other features
- \* Create a standalone SDK that you can distribute to other developers so that they don't have to install the complete build system
- \* Track which open source licenses are used by the various packages you have selected
- \* Allow you to create updates for in-field updating
- \* Have a user-friendly user interface

## >>> Open source build systems

1. Buildroot: An easy-to-use system using GNU make and Kconfig (<http://buildroot.org>)
2. EmbToolkit: A simple system for generating root filesystems; the only one at the time of writing that supports LLVM/Clang out of the box (<https://www.embtoolkit.org>)
3. OpenEmbedded: A powerful system which is also a core component of the Yocto Project and others (<http://openembedded.org>)
4. OpenWrt: A build tool oriented towards building firmware for wireless routers (<https://openwrt.org>)
5. PTXdist: An open source build system sponsored by Pengutronix ([http://www.pengutronix.de/software/ptxdist/index\\_en.html](http://www.pengutronix.de/software/ptxdist/index_en.html))
6. Tizen: A comprehensive system, with emphasis on mobile, media, and in-vehicle devices (<https://www.tizen.org>)
7. The Yocto Project: This extends the OpenEmbedded core with configuration, layers, tools, and documentation: probably the most popular system (<http://www.yoctoproject.org>)

>>> Buildroot

The Buildroot project website is at <http://buildroot.org>.

Current versions of Buildroot are capable of building a toolchain, a bootloader (U-Boot, Barebox, GRUB2, or Gummiboot), a kernel, and a root filesystem. It uses GNU make as the principal build tool.

There is good online documentation at <http://buildroot.org/docs.html>, including The Buildroot User Manual.

>>> Installing

1. `git clone git://git.buildroot.net/buildroot`
2. `cd buildroot`



>>> **Configuring**

1. `cd buildroot`
2. `make qemu_arm_versatile_defconfig`
3. `make`

>>> Running

```
qemu-system-arm -M vexpress-a9 -m 256 -kernel output/images/zImage -dtb  
output/images/vexpress-v2p-ca9.dtb -drive file=output/images/rootfs.ext2,if=sd  
-append "console=ttyAMA0,115200 root=/dev/mmcblk0" -serial stdio -net  
nic,model=lan9118 -net user
```



>>> Adding source

1. modify file package/Config.in
2. create project directory in package directory
3. in project directory create files: Config.in project\_name.mk and directory src
4. move your source files into src directory and create Makefile

```
>>> Adding source
```

```
menu "Misc"  
source "package/hello/Config.in"  
endmenu
```

```
>>> package/hello/Config.in
```

```
config BR2_PACKAGE_HELLO
    bool "hello"
    help
    Hello world package.
```

```
http://example.com
```

```
>>> package/hello/hello.mk

#####
#
# hello
#
#####

HELLO_VERSION = 1.0
HELLO_SITE = ./package/hello/src
HELLO_SITE_METHOD = local

define HELLO_BUILD_CMDS
$(MAKE) CC="$(TARGET_CC)" LD="$(TARGET_LD)" -C $(@D)
endef

define HELLO_INSTALL_TARGET_CMDS
$(INSTALL) -D -m 0755 $(@D)/hello $(TARGET_DIR)/usr/bin
endef

$(eval $(generic-package))
```

```
>>> package/hello/src/Makefile
```

```
CC = gcc
```

```
.PHONY: clean
```

```
hello: hello.c
```

```
$(CC) -o '$@' '$<'
```

```
clean:
```

```
rm hello
```



## >>> Components

1. Poky: The reference distribution
2. oe-core: The core metadata, which is shared with OpenEmbedded
3. BitBake: The task scheduler, which is shared with OpenEmbedded and other projects
4. Documentation: User manuals and developer's guides for each component
5. Hob: A graphical user interface to OpenEmbedded and BitBake
6. Toaster: A web-based interface to OpenEmbedded and BitBake
7. ADT Eclipse: A plug-in for Eclipse that makes it easier to build projects using the Yocto Project SDK

## >>> Installing the Yocto Project

```
git clone -b fido git://git.yoctoproject.org/poky.git
```

>>> **Configuring**

1. `cd poky`

2. `source oe-init-build-env`

`source oe-init-build-env build-qemuarm`

>>> Building

- \* core-image-minimal: A small console-based system which is useful for tests and as the basis for custom images.
- \* core-image-minimal-initramfs: This is similar to core-image-minimal, but built as a ramdisk.
- \* core-image-x11: A basic image with support for graphics through an X11 server and the xterminal terminal app.
- \* core-image-sato: A full graphical system based on Sato, which is a mobile graphical environment built on X11, and GNOME. The image includes several apps including a terminal, an editor, and a file manager.

bitbake core-image-minimal

>>> Running

To run the QEMU emulation, make sure that you have sourced `oe-init-build-env` and then just type:

```
runqemu qemuarm
```

## >>> BitBake and recipes I

- \* **recipes:** Files ending in `.bb`. These contain information about building a unit of software, including how to get a copy of the source code, the dependencies on other components, and how to build and install it.
- \* **append:** Files ending in `.bbappend`. These allow some details of a recipe to be overridden or extended. A `.bbappend` file simply appends its instructions to the end of a recipe (`.bb`) file of the same root name.
- \* **include:** Files ending in `.inc`. These contain information that is common to several recipes, allowing information to be shared among them. The files may be included using the `include` or `require` keywords. The difference is that `require` produces an error if the file does not exist, whereas `include` does not.
- \* **classes:** Files ending in `.bbclass`. These contain common build information, for example how to build a kernel or how to build an autotools project. The classes are inherited and extended in recipes and other classes using the `inherit` key word. The class `classes/base.bbclass` is implicitly inherited in every recipe.
- \* **configuration:** Files ending in `.conf`. They define various configuration variables that govern the project's build process.

## >>> BitBake and recipes II

The default task is `do_build`, so that you are running the build task for that recipe. You can list the tasks available in a recipe by running `bitbake core-image-minimal` like this:

```
bitbake -c listtasks core-image-minimal
```

The `-c` option allows you to specify the task, missing off the `do_` part. A common use is `-c fetch` to get the code needed by a recipe:

```
bitbake -c fetch busybox
```

You can also use `fetchall` to get the code for the target and all the dependencies:

```
bitbake -c fetchall core-image-minimal
```

```
>>> Interesting features
```


- \* `dbg-pkgs`: installs debug symbol packages for all the packages installed in the image.
- \* `debug-tweaks`: allows root logins without passwords and other changes that make development easier.
- \* `package-management`: installs package management tools and preserves the package manager database.
- \* `read-only-rootfs`: makes the root filesystem read-only.
- \* `x11`: installs the X server.
- \* `x11-base`: installs the X server with a minimal environment.
- \* `x11-sato`: installs the OpenedHand Sato environment



## >>> Further reading

- \* The Buildroot User Manual, <http://buildroot.org/downloads/manual/manual.html>
- \* Yocto Project documentation: there are nine reference guides plus a tenth which is a composite of the others (the so-called Mega-manual") at <https://www.yoctoproject.org/documentation>
- \* Instant Buildroot, by Daniel Manchón Vizuete, Packt Publishing, 2013
- \* Embedded Linux Development with Yocto Project, by Otavio Salvador and Daianne Angolini, Packt Publishing, 2014

## >>> References

 C. Simmonds.  
*Mastering Embedded Linux Programming.*  
Packt Publishing, 2015.