

Biologically-inspired algorithms and models

7. Cooperative and competitive coevolution

Maciej Komosinski

Coevolution

Cooperative
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Competitive
coevolution

References

Many species (groups of organisms) – at least two – influence each other's evolutionary processes.

Question: How does this affect the fitness function landscape?

A famous competitive example: [predators and prey – the Lotka–Volterra model](#)

Fundamental issues in cooperative optimization

Cooperative coevolution

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The example of the cooperative architecture discussed in this section is based on [PD00].

The implementation of this architecture is available in the DEAP

library: https://deap.readthedocs.io/en/master/examples/coev_coop.html.

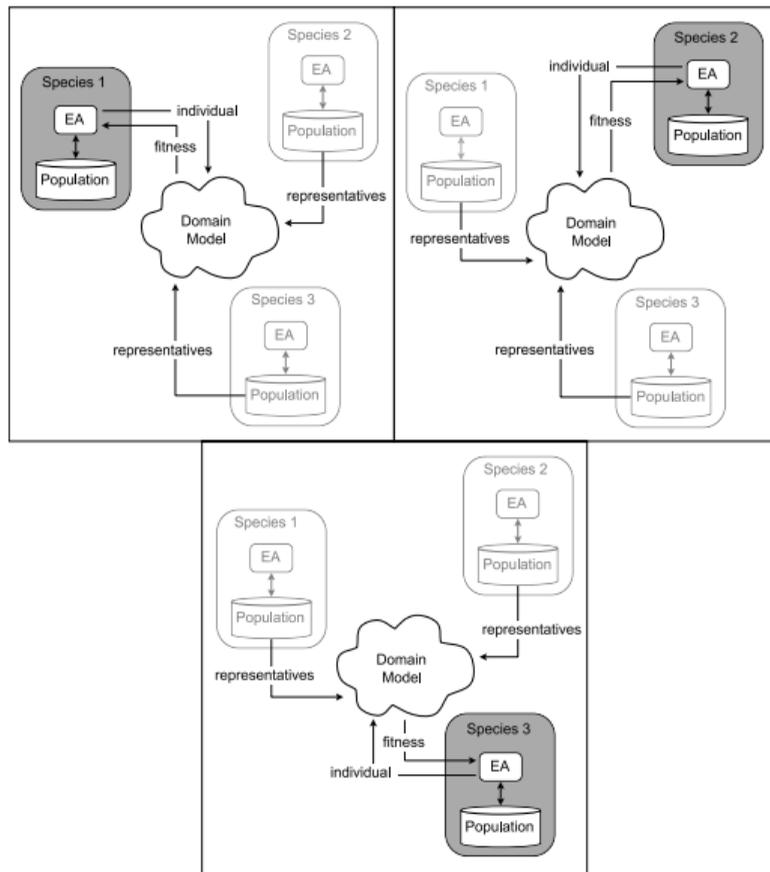
- The optimization of complex problems will be more effective if we can decompose them into components.
- As we know from previous lectures (cf. epistasis, hierarchical GA), unfortunately, the effect of different parts of a solution on the value of the objective function is usually strongly coupled.
- In a traditional EA, individuals are evaluated completely independently – so there is no room for them to cooperate with each other.
- If we managed to decompose the problem (even manually, for example by splitting the individual – the vector of variables – into individual variables), we would have to solve the following problems: 1) the dependence of the fitness landscape from the point of view of each component on the values of other cooperating components, 2) attributing credit to components (*credit assignment*), 3) maintaining diversity within the population of components.
- Suppose we divide the solution into components that go into separate (genetically independent) populations – so the genetic representation and operators in each population may be completely different. How do we evaluate the quality of each part?

The architecture explored by Potter and De Jong

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Adaptation of the number of species

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- For a function with n variables, we can hand-decompose the task into n species.
- For an agent (e.g. a robot) with a rule-based control system, we can hand-decompose the set of rules into two species, each for a class of behaviors: finding the target and waiting for the target to appear.
- Considering a task in which the number of components can change dynamically, it would be great if the algorithm itself could adjust the number of species and their function (\rightarrow “niches” ...) in cooperation with other species. What could trigger the addition of a new species and the removal of an existing one?
 - Adding a new species, for example initialized randomly: when the system is in stagnation – no increase in the quality of the best individual.
 - Removing an existing species: for example when its contribution to cooperation (the difference between the quality of individuals with and without it) is below a specified threshold.

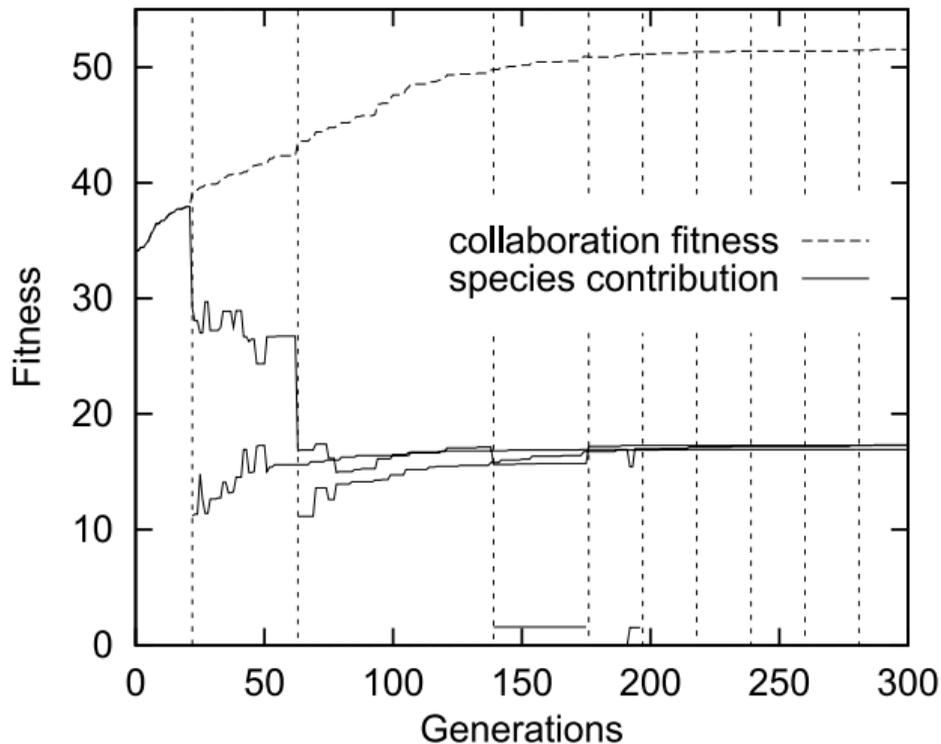
[PD00] Experiment 1: binary string covering – coevolutionary run

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Automatically determined number of species; vertical lines are the generations when a species was added as a result of detected stagnation (22, 63, 138) or removed due to its small contribution (oscillations starting from 176).

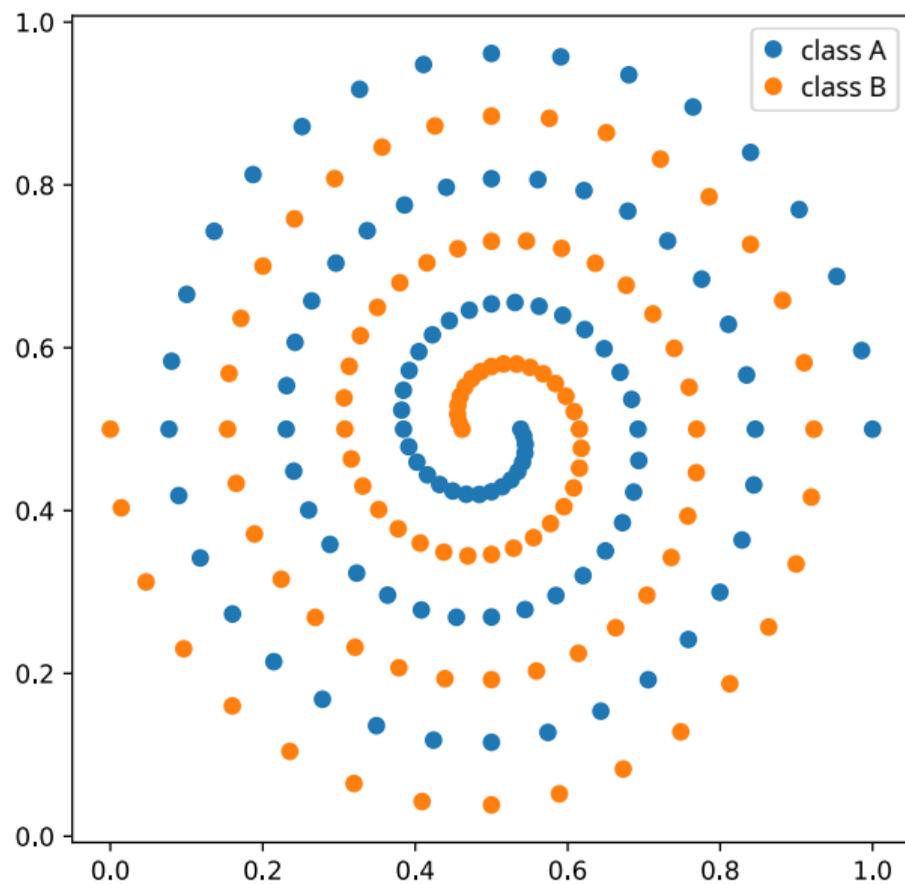


[PD00] Experiment 2: classification of a tricky dataset

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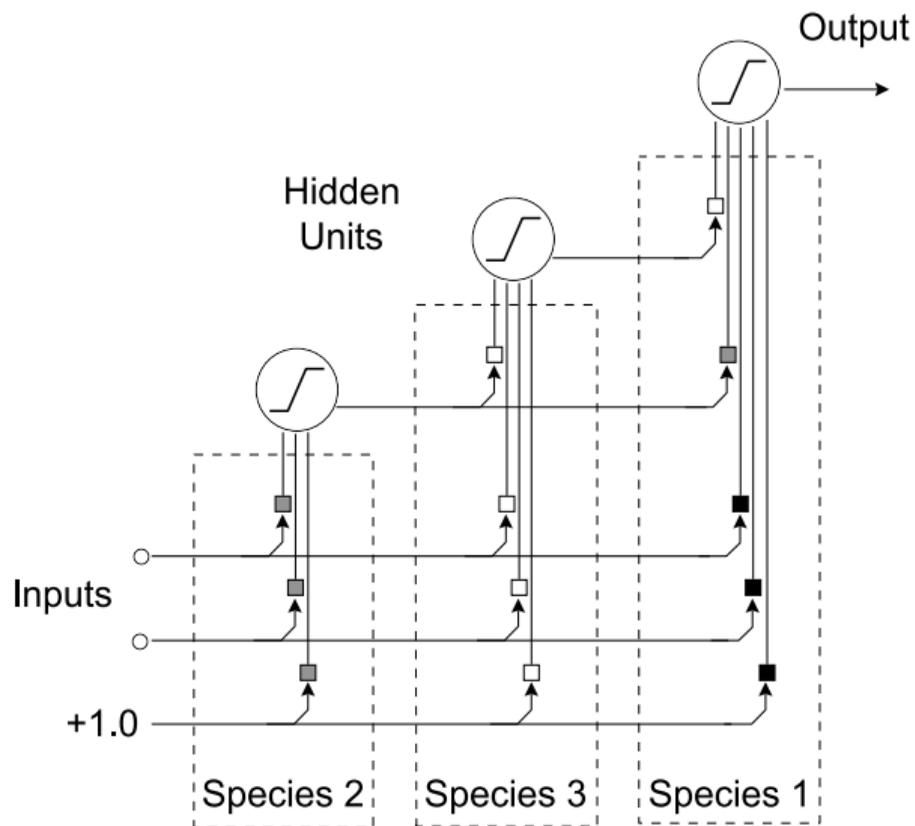
[PD00] Experiment 2: classification of a tricky dataset

Cascade-correlation NN (cf. [gradient boosting](#)): a simple heuristic as a reference and coevolving species

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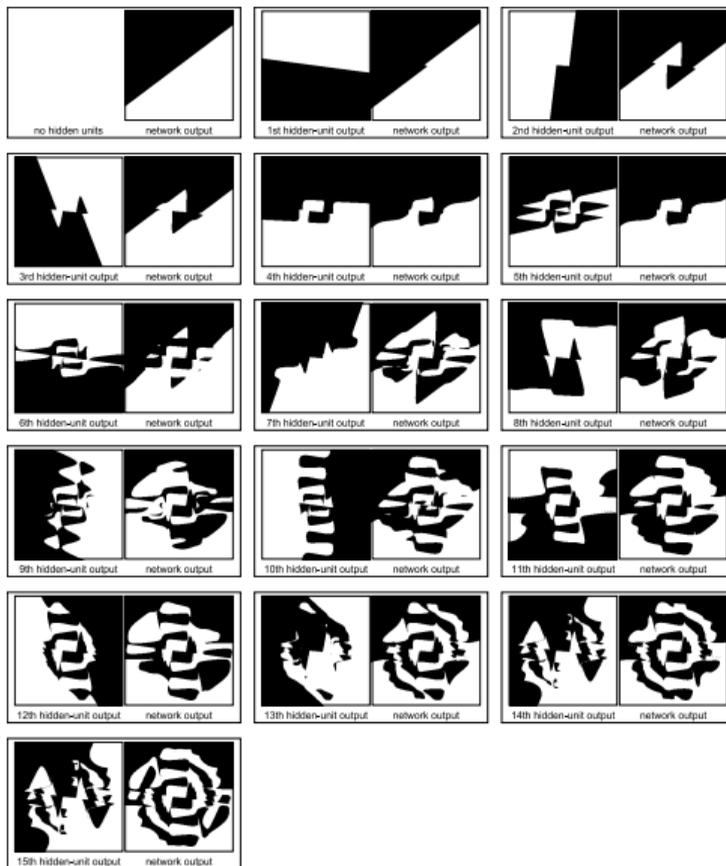
[PD00] Experiment 2: classification of a tricky dataset

Cascade neural network results: the training heuristic

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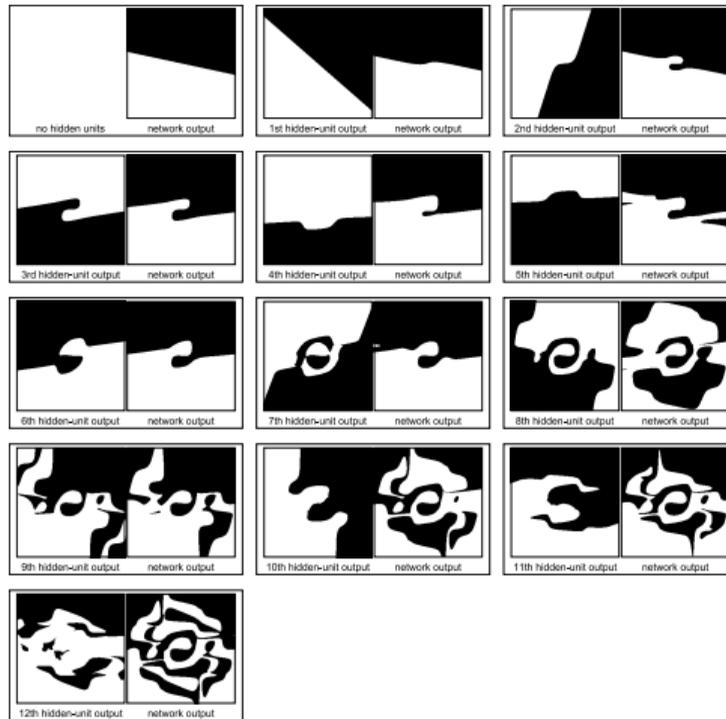
[PD00] Experiment 2: classification of a tricky dataset

Cascade neural network results: cooperative coevolution

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Competitive coevolution – the desired behavior

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A typical example: coevolution (optimization) of a strategy [Elf+21]. An individual represents the knowledge reflected by a strategy (e.g., it may be the weights of the criteria used to evaluate the situation on the board in a game). The evaluation of an individual is obtained, for example, by playing many games against the other individuals (each playing according to their own strategy).

Discussion: if we start such a process and wait long enough, do we get the master strategy? If not, why not? (provide reasons – the list of possible problems).

Difficulties: we want an *arms race* (perpetual competition), but we may end up in an *MSS – Mediocre Stable State* (stagnation – poor, lasting condition). Too strong an opponent will not allow distinguishing between average and bad solution; too weak – between average and good. The evaluation of each solution depends on the others (an external, objective “teacher” solves this problem while eliminating the advantages of coevolution). The evaluation of a strategy may not be transitive.

Competitive coevolution – problems and remedies

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- Discussion of sample scenarios: GP (a population of expressions and a population of tests [ML analogy]), chess playing strategies, soccer, tennis and the intransitivity of “betterness”, rock–paper–scissors, a local fencing school and diversity (cf. *exploiter agents* in AlphaStar), nature.
- Concepts: arms race*, Red Queen**, MSS.
- Problems: the lack of or the loss of gradient, looping (cycles, non-transitive relation of comparison that arises from evaluation), the lack of monotonicity/progress [Mic09].
- Remedies: *competitive fitness sharing* (increasing the value of those solutions that win against tests (opponents) difficult for other solutions [RB95]), a specific selection of the test set, maintaining *hall of fame* or sets of Pareto-nondominated solutions and tests.

*https://en.wikipedia.org/wiki/Evolutionary_arms_race

**https://en.wikipedia.org/wiki/Red_Queen_hypothesis

References I

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References

- [Elf+21] Ehab Z. Elfeky et al. “A systematic review of coevolution in real-time strategy games”. In: *IEEE Access* 9 (2021), pp. 136647–136665. URL: <https://ieeexplore.ieee.org/stamp/stamp.jsp?arnumber=9548932>.
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- [PD00] Mitchell A. Potter and Kenneth A. De Jong. “Cooperative coevolution: an architecture for evolving coadapted subcomponents”. In: *Evolutionary computation* 8.1 (Mar. 2000), pp. 1–29. DOI: 10.1162/106365600568086. URL: <http://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.35.5861&rep=rep1&type=pdf>.
- [RB95] Christopher Rosin and Richard Belew. “Methods for competitive co-evolution: finding opponents worth beating”. In: *Proceedings of the Sixth International Conference on Genetic Algorithms*. Morgan Kaufmann, 1995, pp. 373–380. URL: <https://citeseerx.ist.psu.edu/viewdoc/download?doi=10.1.1.52.9359&rep=rep1&type=pdf>.