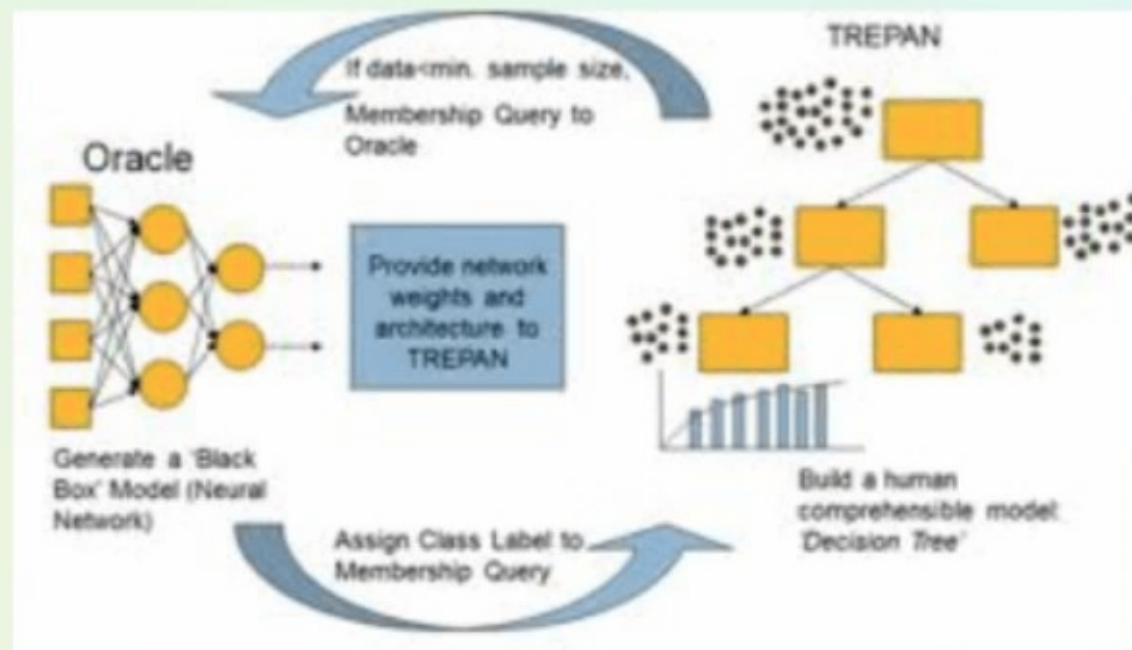
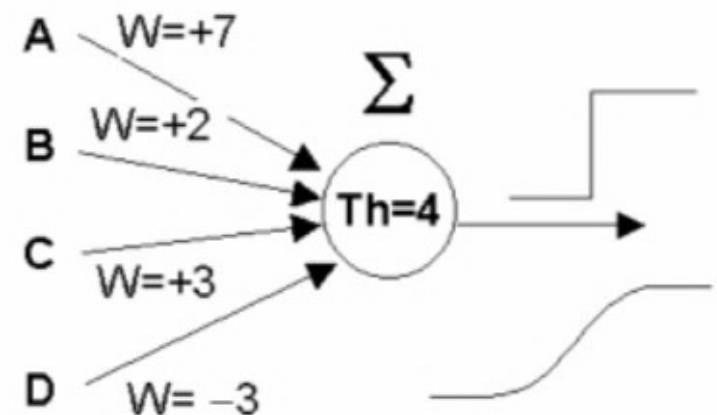


Tworzenie interpretowalnych reprezentacji zastępczych dla złożonych modeli (ANN)



IF{ (A and B) or (A and C) or
(A and not D) and
(A and B and C) and
(B and C and not D) }
THEN True
ELSE False



Deconvolution of CNN and other visualizations of internal layers

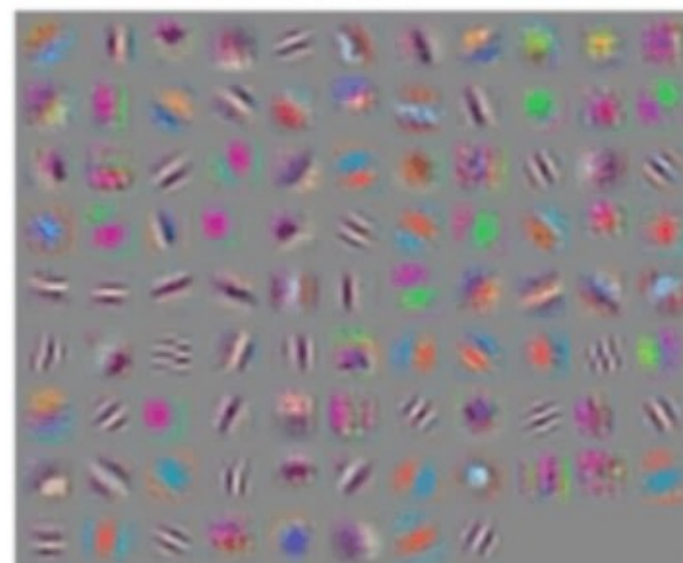
conv1



conv2



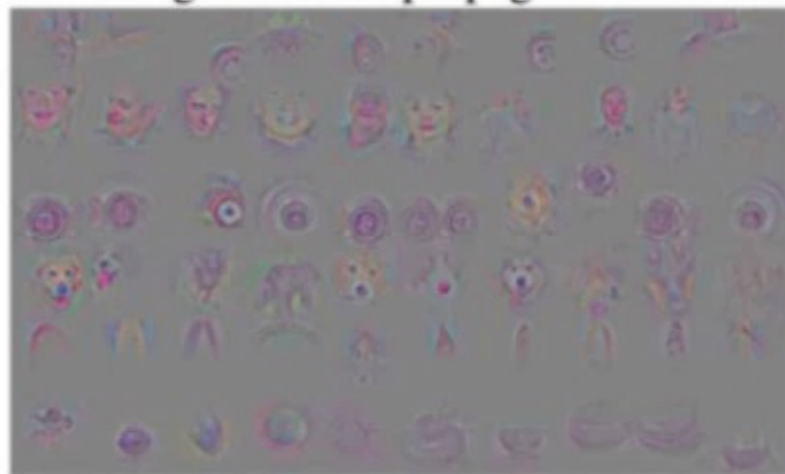
conv3



deconv



guided backpropagation



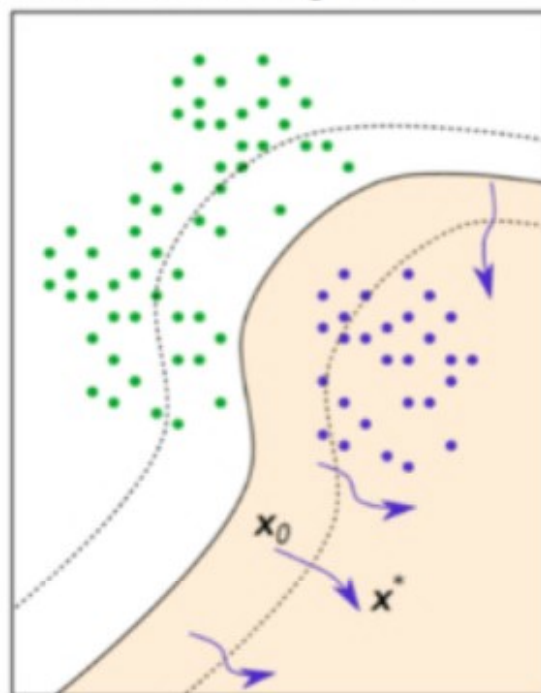
corresponding image crops



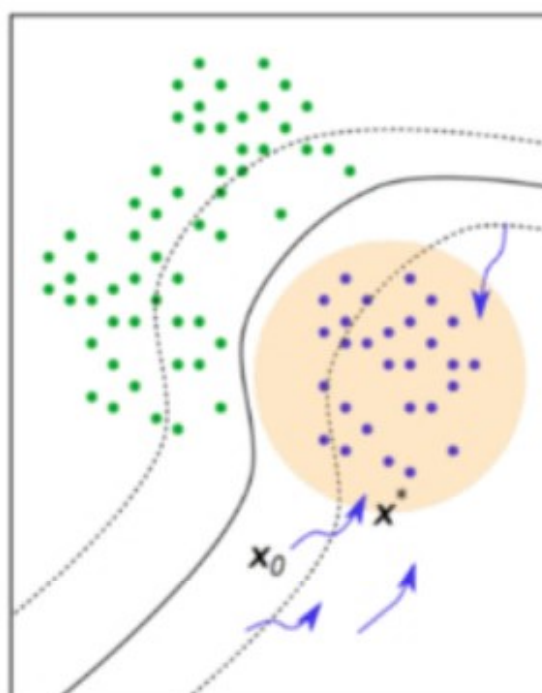
Jost Tobias Springenberg, Alexey Dosovitskiy, Thomas Brox & Martin Riedmiller 2014. Striving for simplicity: The all convolutional net. [arXiv:1412.6806](https://arxiv.org/abs/1412.6806).

Skupienie uwagi na przykładach

model analysis

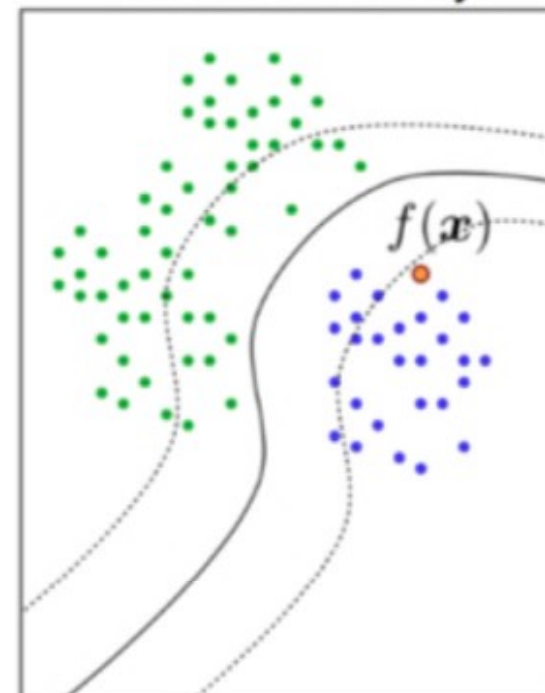


Find the input pattern that maximizes class probability.



Find the most likely input pattern for a given class.

decision analysis

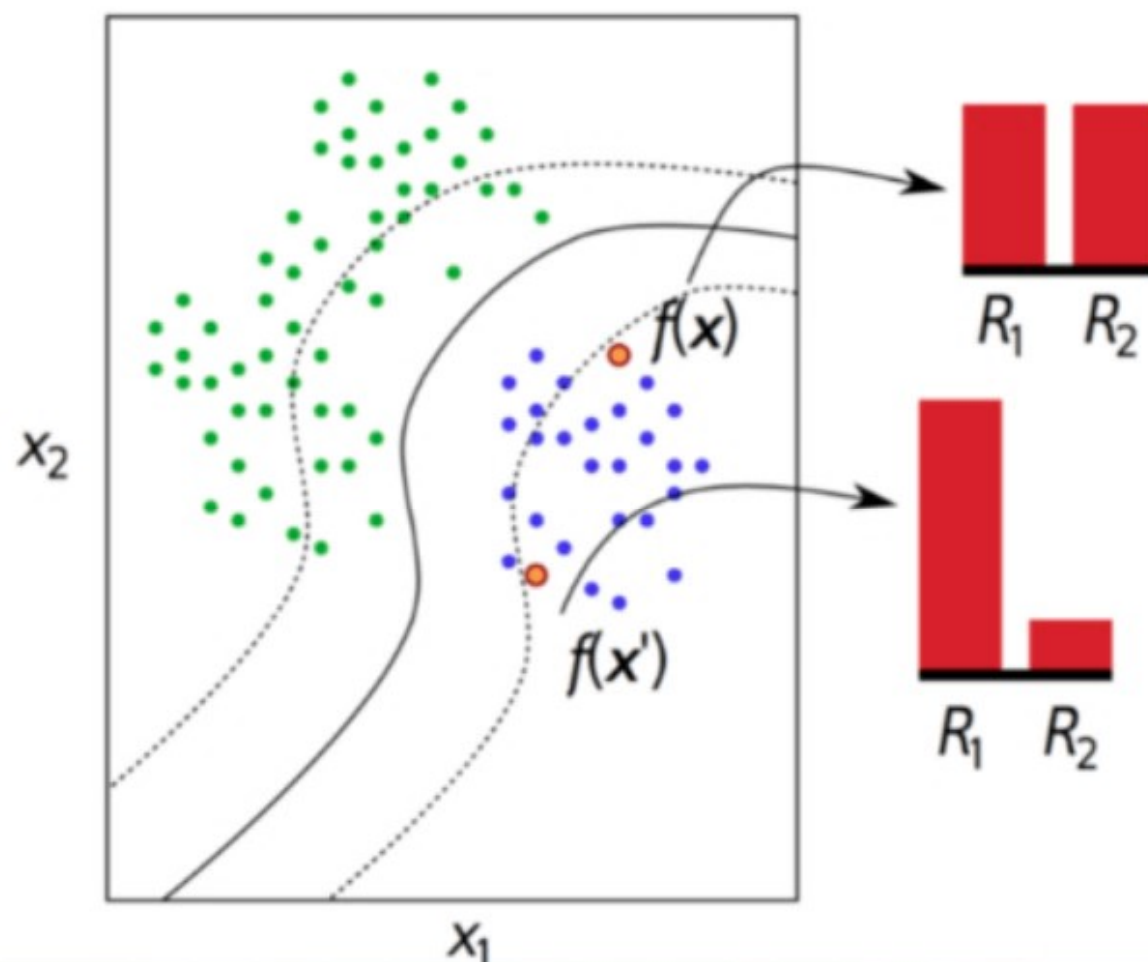


Explain individual prediction.

Różne możliwości / za wykładem W.Samek

Explaining Individual Decisions

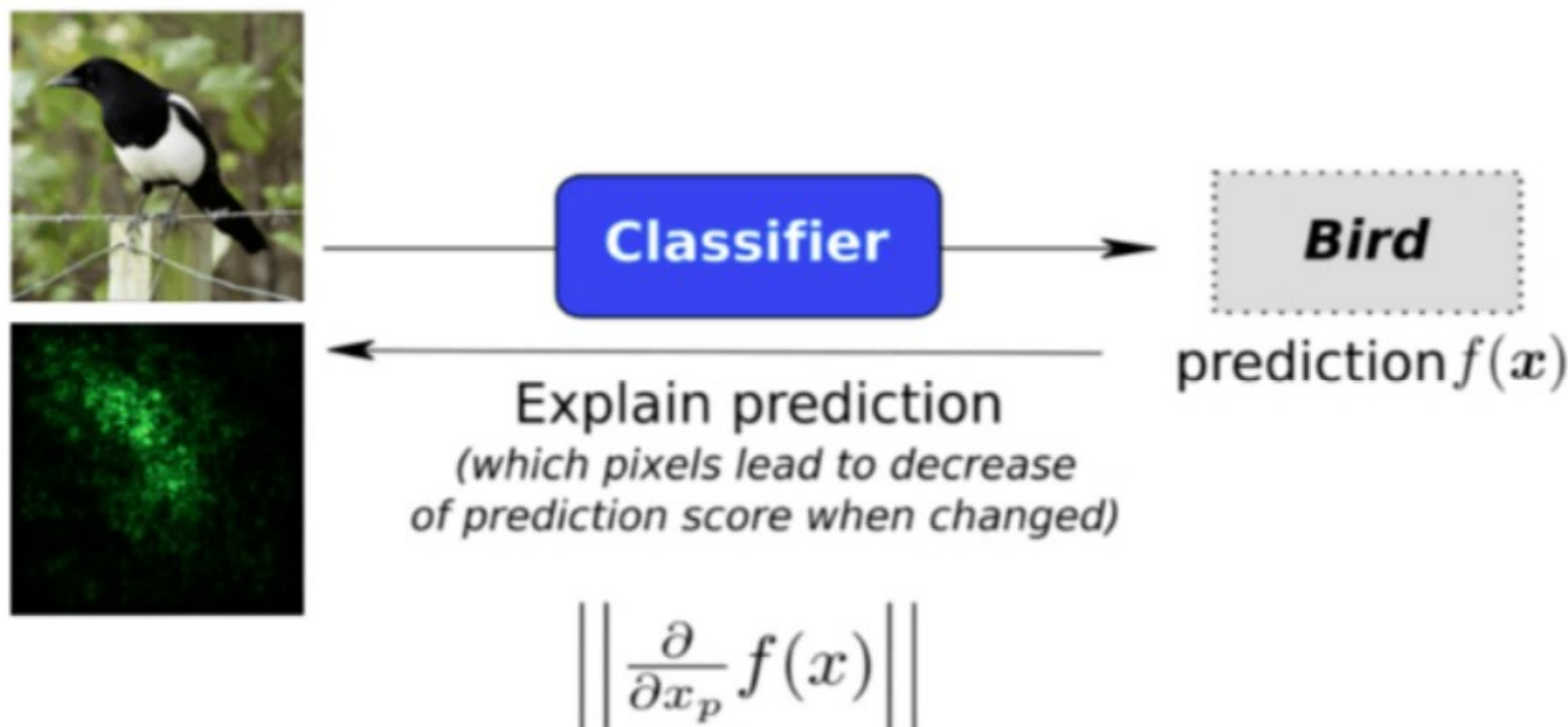
Goal: Determine the relevance of each input variable for a given decision $f(x_1, x_2, \dots, x_d)$, by assigning to these variables *relevance scores* $R_1, R_2, \dots, R_d$.



Poszukiwanie krytycznych elementów w danych

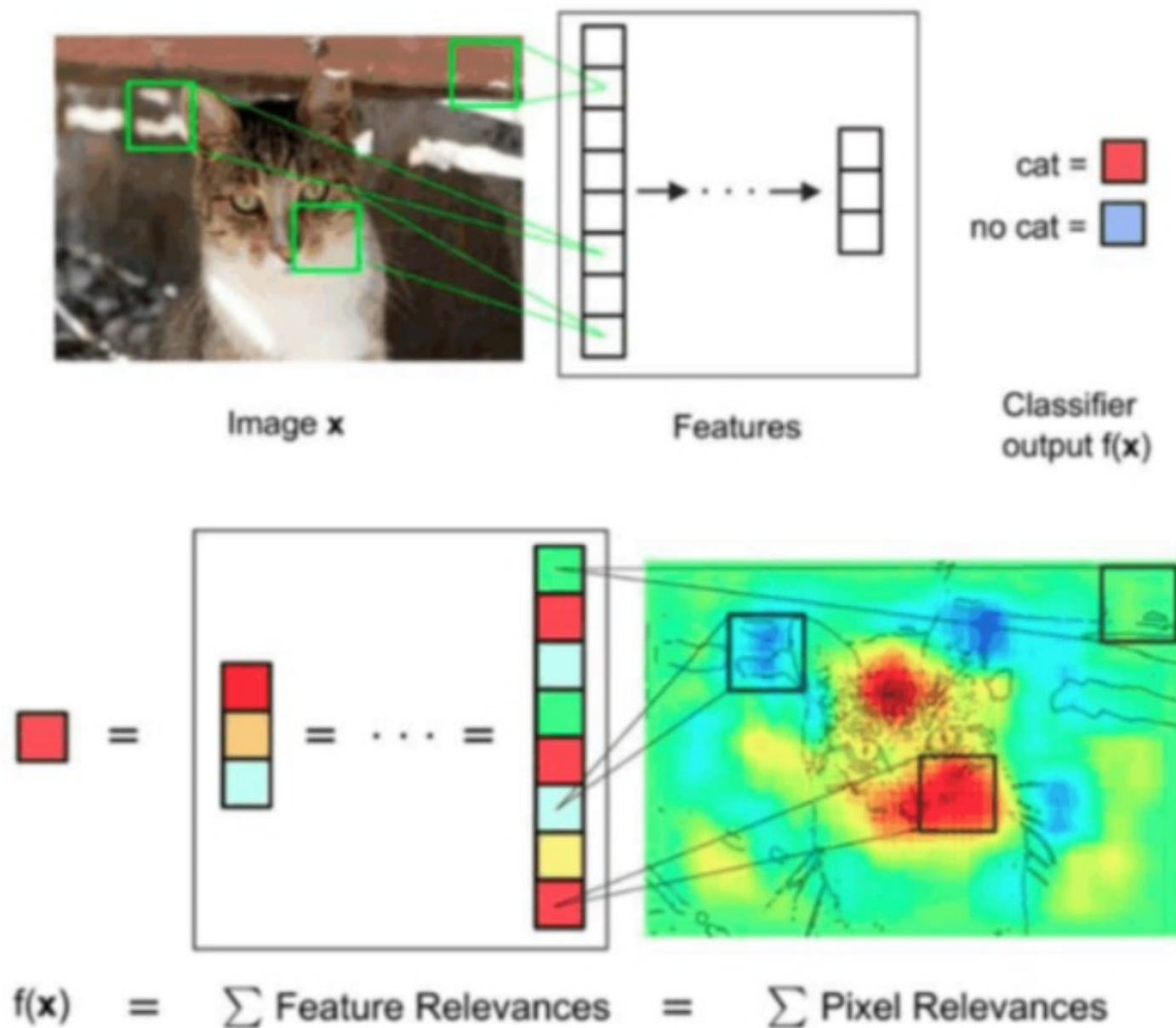
Techniques of Interpretation

Sensitivity Analysis
(Simonyan et al. 2014)



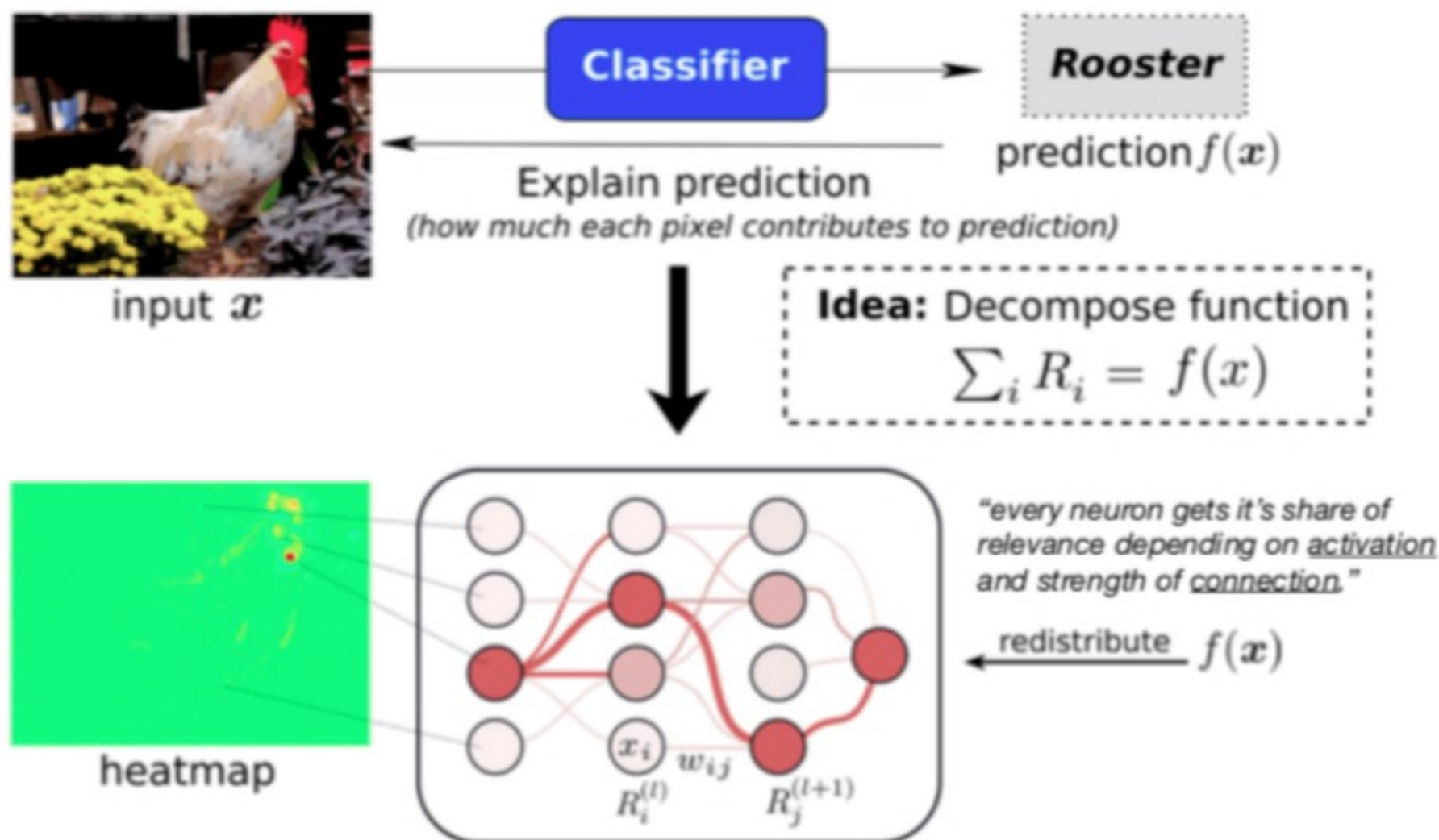
Specyfika wyjaśnień obrazowych

Sebastian Bach, Alexander Binder, Grégoire Montavon, Frederick Klauschen, Klaus-Robert Müller & Wojciech Samek 2015. On pixel-wise explanations for non-linear classifier decisions by layer-wise relevance propagation. PLoS one, 10, (7), e0130140, doi:10.1371/journal.pone.0130140.



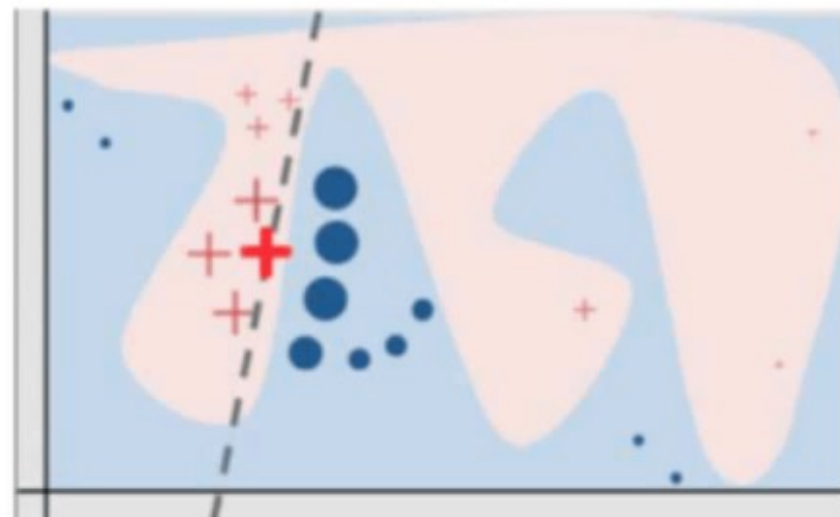
Techniques of Interpretation

Layer-wise Relevance Propagation (LRP)
(Bach et al. 2015)

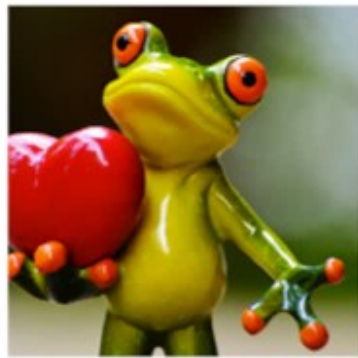


What are explanations in the sense of LIME ?

- Explanation := local linear approximation of the model's behaviour. While the model may be very complex globally, it is easier to approximate it around the vicinity of a particular instance. While treating the model as a black box, we perturb the instance we want to explain and learn a sparse linear model around it -> used as explanation.
- Look at the image: The model's decision function is represented by the blue/pink background = clearly nonlinear. The bright red cross is the instance being explained (let's call it X). We sample instances around X, and weight them according to their proximity to X (weight here is indicated by size). We then learn a linear model (dashed line) that approximates the model well in the vicinity of X, but not necessarily globally!

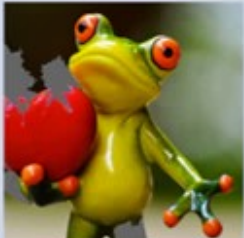


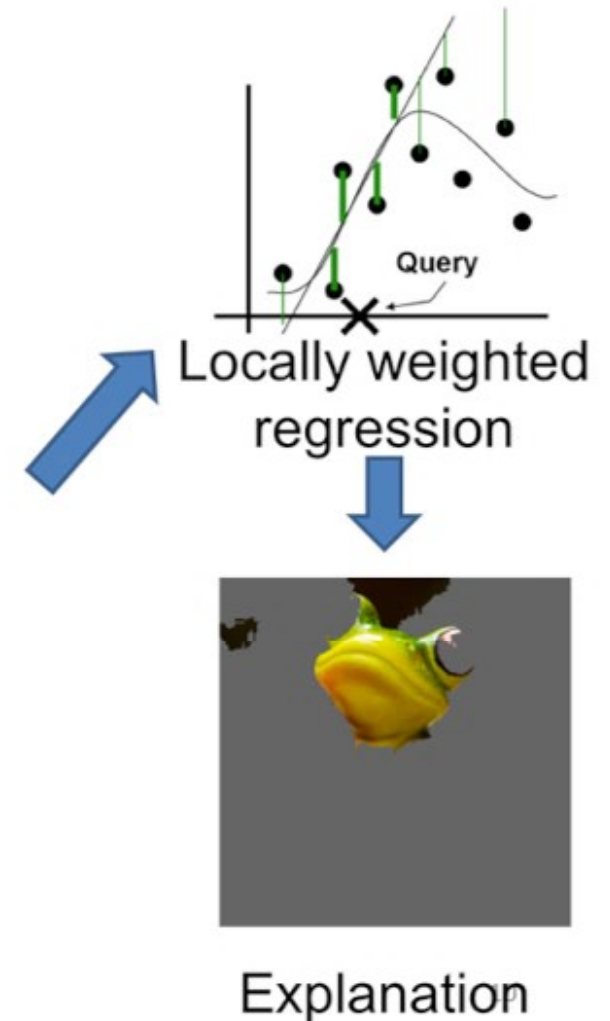
LIME – rozpoznawanie obrazów



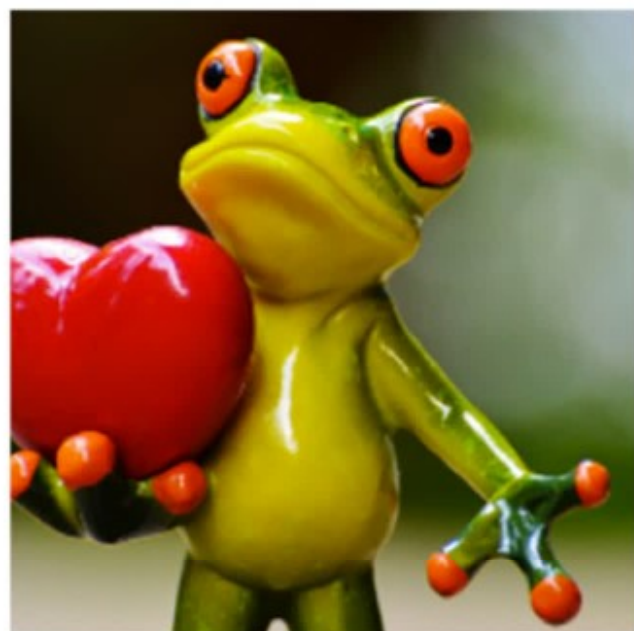
Original Image
 $P(\text{tree frog}) = 0.54$



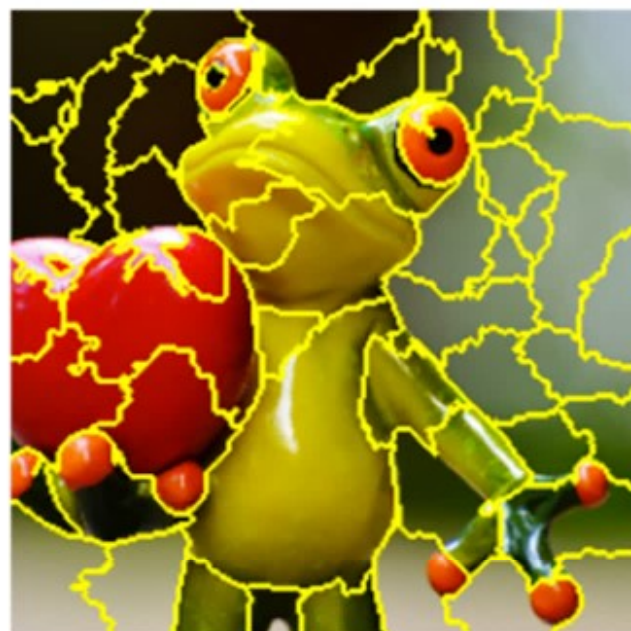
Perturbed Instances	$P(\text{tree frog})$
	 0.85
	 0.00001
	 0.52



LIME – rozpoznawanie obrazów



Original Image



Interpretable
Components

LIME – rozpoznawanie obrazów



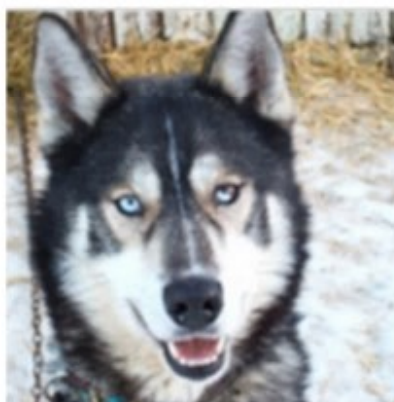
Predicted: **wolf**
True: **wolf**



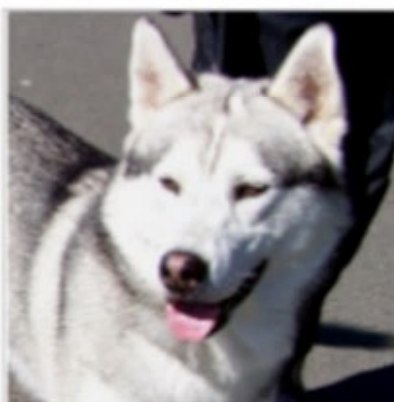
Predicted: **husky**
True: **husky**



Predicted: **wolf**
True: **wolf**



Predicted: **wolf**
True: **husky**



Predicted: **husky**
True: **husky**



Predicted: **wolf**
True: **wolf**

LIME – rozpoznawanie obrazów



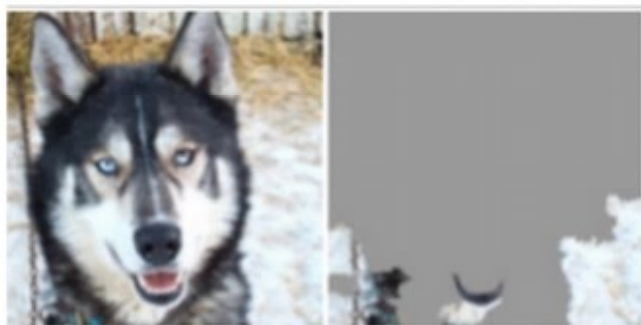
Predicted: **wolf**
True: **wolf**



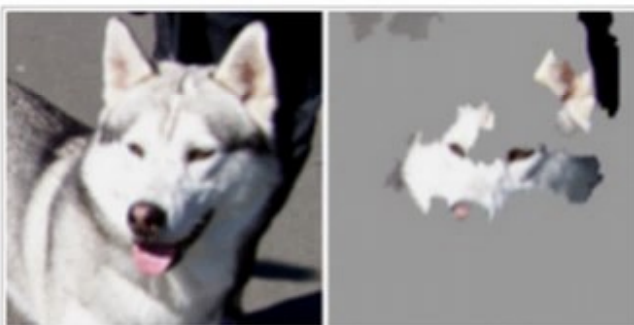
Predicted: **husky**
True: **husky**



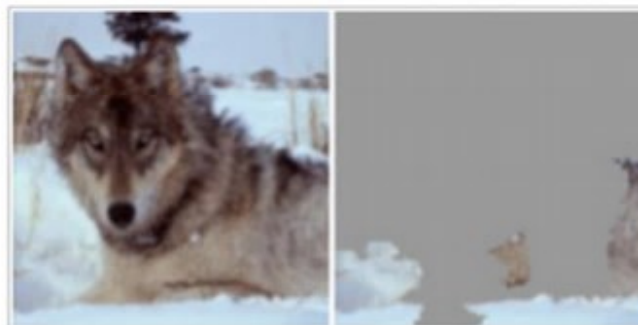
Predicted: **wolf**
True: **wolf**



Predicted: **wolf**
True: **husky**



Predicted: **husky**
True: **husky**



Predicted: **wolf**
True: **wolf**

LIME

