

Overview

- Evolving partial programs with *holes* (sketches) [1].
- Evolution responsible for program *structure*, SMT solver fills in the gaps with short code pieces.
- This paper: single-instruction holes.
- Improves over standard GP and works particularly well for constants.

<https://github.com/iwob/EPS>

SMT solving (Satisfiability Modulo Theories)

- Checking if a formula is satisfiable under a certain theory T .
- *Theory* describes mathematical objects and semantics of functions that operate on them (e.g. integer numbers and $+$, $-$, $*$, \div , mod) and includes decision procedures for reasoning.
- *Model* contains valuation of variables which make the formula satisfiable.

Examples:

$(10 \cdot x = 20) \wedge a$
SAT
 $x = 2, a = true$

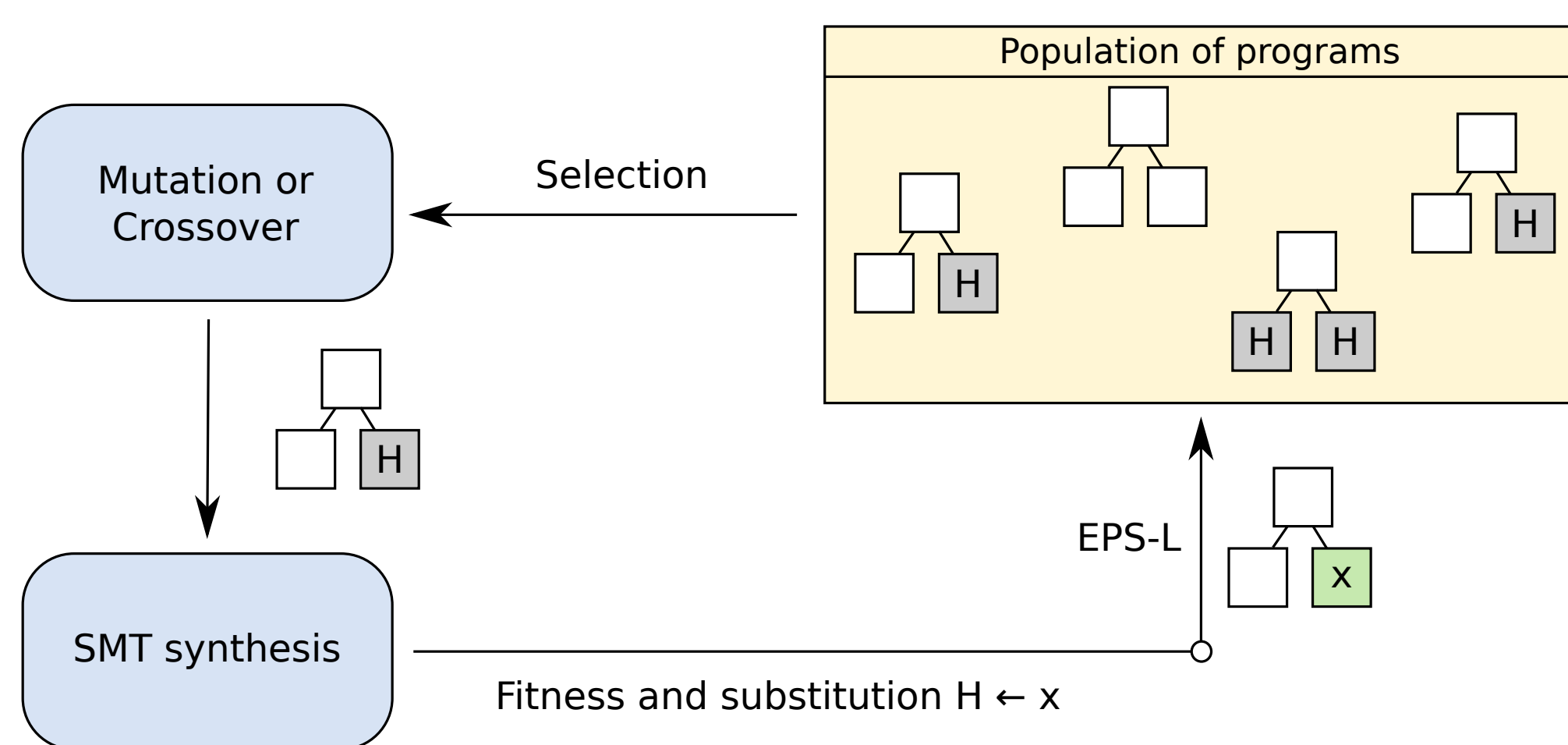
$(x < y) \wedge (y > x)$
UNSAT

$x^2 + 1 \leq 2 \cdot x$
SAT
 $x = 1$

$\forall x,y (x + y)^2 > x^2 + y^2$
UNSAT

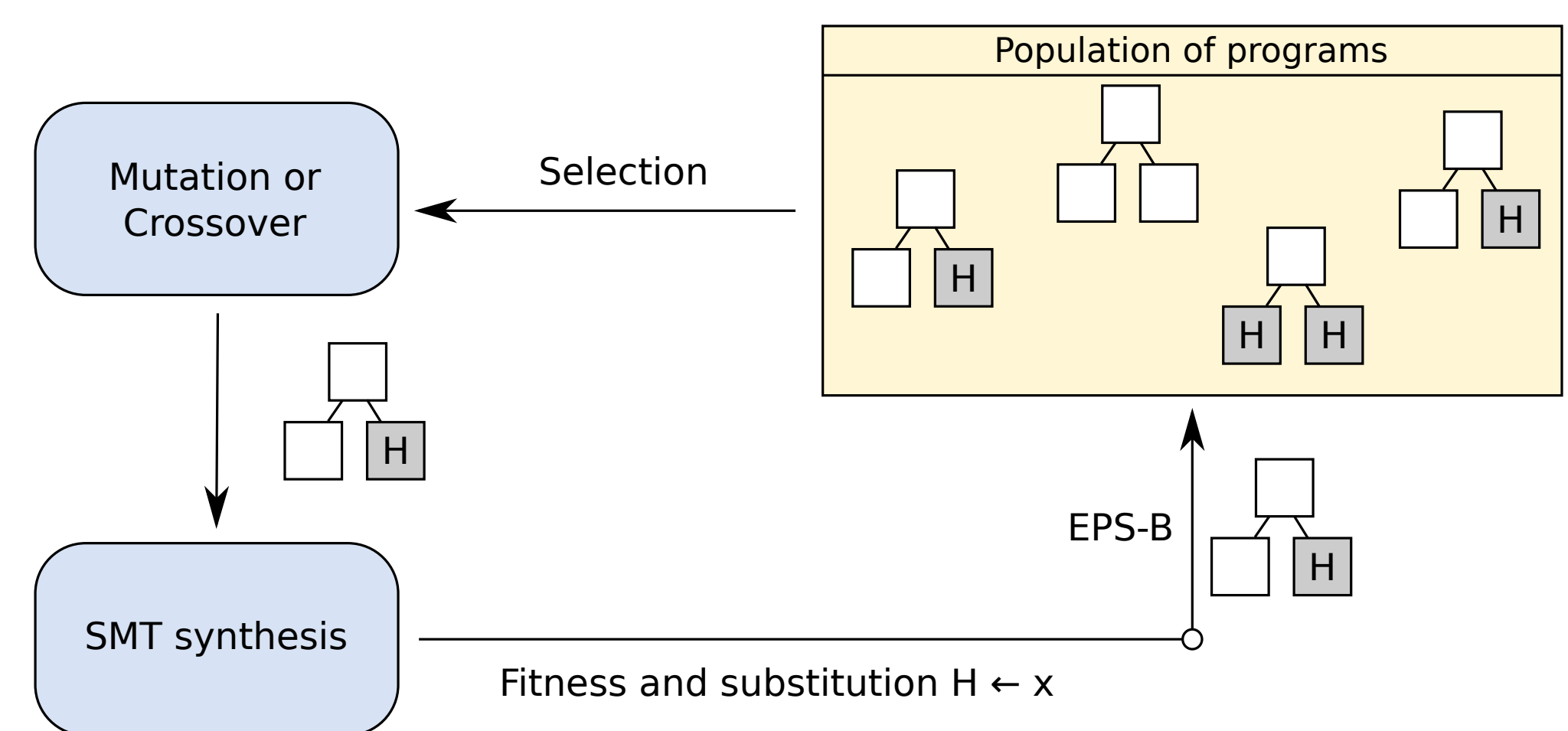
EPS-L (“Lamarckian” EPS)

Holes are filled with the content discovered by the solver.
New holes may be introduced only by mutation.



EPS-B (“Baldwinian” EPS)

Holes remain in the program.
Content discovered by the solver is used only for computing fitness.



Evaluation in EPS

SMT-LIB script

```
(set-option :produce-assignments true)
(set-logic QF_NIA)
; Free variables
(declare-fun int0 () Int)
(declare-fun int1 () Int)
(declare-fun int2 () Int)
; -----
; CONSTRAINTS FOR ALL TEST CASES:
; -----
; DECLARATIONS: Local variables (T0)
(define-fun x_T0 () Int -3)
(declare-fun res_T0 () Int)
; PROGRAM (T0)
(assert (! (= res_T0 (* (* int0 x_T0) (+ x_T0 int1)) int2))
        :named T0_p0))
; POSTCONDITION (T0)
(define-fun itest0 () Int (ite (! (= res_T0 8))
                              :named pass_itest0) 1 0))
; ... (other test cases) ...
; DECLARATIONS: Local variables (T6)
(define-fun x_T6 () Int 3)
(declare-fun res_T6 () Int)
; PROGRAM (T6)
(assert (! (= res_T6 (* (* int0 x_T6) (+ x_T6 int1)) int2))
        :named T6_p0))
; POSTCONDITION (T6)
(define-fun itest6 () Int (ite (! (= res_T6 8))
                              :named pass_itest6) 1 0))
; -----
(declare-fun fitness () Int)
(assert (= fitness (+ itest0 ... itest6)))
(maximize fitness)(check-sat)
```

Sketch of the program
 $(int_0 \cdot x) \cdot (int_1 \cdot x) \cdot int_2$

Target function
 $x^2 - 1$

Benchmarks (x, out)
 $(-3, 8), (-2, 3), (-1, 0),$
 $(0, -1), (1, 0), (2, 3), (3, 8).$

SMT solver
Z3

Model and fitness

```
sat
(objectives
 (fitness 2)
)
((int0 0))
((int1 1))
((int2 (- 1)))
```

EPS-L
 $(0 \cdot x) \cdot (1 \cdot x) \cdot (-1)$

EPS-B
 $(int_0 \cdot x) \cdot (int_1 \cdot x) \cdot int_2$

Experiment configuration

Evolution parameters:

- Runs per configuration: 100
- Number of generations: 100
- Population size: 250
- Mutation (0.5) and crossover (0.5)
- Solver timeout [ms]: 1500

Tested variants:

- GP : standard GP.
- GP_T : GP with time limit similar to EPS.
- GP_{5000} : GP with population size 5000.
- c : holes can be filled with constants.
- v : holes can be filled with input variables.
- cv : both constants and variables.

Results

Number of optimal solutions found (per 100 runs)

| | GP | | | EPS-L | | | EPS-B | | |
|------------|----|-----------------|--------------------|-------|---|----|-------|----|-----|
| | GP | GP _T | GP ₅₀₀₀ | c | v | cv | c | v | cv |
| Keijzer12 | 0 | 0 | 5 | 0 | 0 | 1 | 39 | 1 | 0 |
| Kozal | 19 | 68 | 96 | 33 | - | 32 | 100 | - | 100 |
| Kozal-p | 0 | 0 | 0 | 5 | - | 3 | 100 | - | 100 |
| Kozal-2D | 1 | 12 | 20 | 2 | 0 | 11 | 80 | 21 | 23 |
| Kozal-p-2D | 0 | 0 | 0 | 0 | 0 | 1 | 75 | 0 | 0 |

Average runtime [s]

| | GP | | | EPS-L | | | EPS-B | | |
|------------|----|-----------------|--------------------|-------|-----|------|-------|-------|-------|
| | GP | GP _T | GP ₅₀₀₀ | c | v | cv | c | v | cv |
| Keijzer12 | 15 | 11331 | 493 | 772 | 488 | 1579 | 15440 | 21173 | 28354 |
| Kozal | 5 | 291 | 46 | 700 | - | 801 | 652 | - | 696 |
| Kozal-p | 5 | 963 | 344 | 892 | - | 972 | 978 | - | 982 |
| Kozal-2D | 16 | 7636 | 432 | 793 | 479 | 1791 | 9077 | 16281 | 23034 |
| Kozal-p-2D | 15 | 9206 | 515 | 750 | 511 | 1726 | 11986 | 12391 | 27875 |

Acknowledgments

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References

- [1] Armando Solar-Lezama. “Program sketching”. In: *International Journal on Software Tools for Technology Transfer* 15.5 (2013), pp. 475–495.