## Learning Eigenvectors for Free

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### From learning vectors to learning matrices

 Machine learning is traditionally interested in learning vector parameters (e.g. regression, classification)

$$oldsymbol{x} = egin{pmatrix} x_1 \ x_2 \ dots \ x_n \end{pmatrix} oldsymbol{w} = egin{pmatrix} w_1 \ w_2 \ dots \ w_n \end{pmatrix}$$

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 Recent interest in matrix generalizations of classical prediction tasks (PCA, learning kernels, learning subspaces)

$$\boldsymbol{X} = \begin{pmatrix} x_{1,1} & x_{1,2} \cdots & x_{1,n} \\ x_{2,1} & x_{2,2} \cdots & x_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n,1} & x_{n,2} \cdots & x_{n,n} \end{pmatrix} \qquad \boldsymbol{W} = \begin{pmatrix} w_{1,1} & w_{1,2} \cdots & w_{1,n} \\ w_{2,1} & w_{2,2} \cdots & w_{2,n} \\ \vdots & \vdots & \ddots & \vdots \\ w_{n,1} & w_{n,2} \cdots & w_{n,n} \end{pmatrix}$$

## The open problem (Warmuth, COLT 2007)

- In each case the matrix generalizations have performance guarantees (worst-case regret bounds) identical to the classical tasks
- Matrices have n<sup>2</sup> parameters and vectors n parameters. Thus matrices should be harder to learn!

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#### Predicting *n*-ary sequence with logarithmic loss

- Many interpretations: forecasting, data compression, investment
- Simple but fundamental
- Extremely well-studied
- We generalise the problem and lift the algorithms to the matrix domain.
- We prove and explain a



#### 1 Introduction

- 2 Classical Log Loss
- 3 Matrix Log Loss
- 4 Free Matrix Lunch
- 5 Summary and Open Questions

# Predicting outcomes from individual *n*-ary sequence (a.k.a. universal coding for *n*-ary alphabet)

for trial t = 1, 2, ... do Alg predicts with a distribution  $\omega_t$  on *n*-ary alphabet Nat reveals an outcome  $x_t \in \{1, ..., n\}$ Alg incurs loss  $-\log \omega_t(x_t)$ end for

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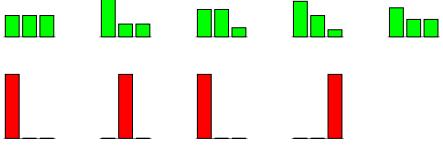
for trial t = 1, 2, ... do Alg predicts with probability vector (distribution)  $\omega_t$ Nat reveals a basis vector  $x_t \in \{e_1, ..., e_n\}$ 

Alg incurs loss  $-\log(\boldsymbol{\omega}_t^{\scriptscriptstyle op} \boldsymbol{x}_t)$ 

end for

# Predicting outcomes from individual n-ary sequence (a.k.a. universal coding for n-ary alphabet)

for trial t = 1, 2, ... do Alg predicts with probability vector (distribution)  $\omega_t$ Nat reveals a basis vector  $x_t \in \{e_1, ..., e_n\}$ Alg incurs loss  $-\log(\omega_t^T x_t)$ end for



## Evaluation

Regret is the cumulative loss of Alg minus the loss of the best fixed distribution (prediction):

$$\mathcal{R}_T \coloneqq \sum_{t=1}^T -\log\left(oldsymbol{\omega}_t^{ op}oldsymbol{x}_t
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ight).$$

The best distribution ω<sup>\*</sup> = arg min Σ<sup>T</sup><sub>t=1</sub> − log (ω<sup>T</sup>x<sub>t</sub>) is the maximum likelihood estimator, while the loss of ω<sup>\*</sup> is the empirical Shannon entropy:

$$oldsymbol{\omega}^{*} = rac{1}{T}\sum_{t=1}^{T}oldsymbol{x}_{t}, \qquad \inf_{oldsymbol{\omega}}\sum_{t=1}^{T} -\log\left(oldsymbol{\omega}^{ op}oldsymbol{x}_{t}
ight) \; = \; T\,H\left(oldsymbol{\omega}^{*}
ight)$$

Goal: design online algorithms with low worst-case regret

Laplace predictor:

$$\boldsymbol{\omega}_{t+1} \coloneqq \frac{\sum_{q=1}^{t} \boldsymbol{x}_q + 1}{t+n} \qquad \mathcal{R}_T \leq (n-1)\log T + O(1)$$

#### Laplace predictor:

$$\boldsymbol{\omega}_{t+1} \coloneqq \frac{\sum_{q=1}^{t} \boldsymbol{x}_q + 1}{t+n} \qquad \mathcal{R}_T \leq (n-1)\log T + O(1)$$

#### Krychevsky-Trofimoff (KT) predictor:

$$\omega_{t+1} \coloneqq \frac{\sum_{q=1}^{t} x_q + 1/2}{t + n/2} \qquad \mathcal{R}_T \leq \frac{n-1}{2} \log T + O(1)$$

Minimax regret achieved by Shtarkov (NML) algorithm:

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Last Step Minimax algorithm

$$\mathcal{R}_T \leq \frac{n-1}{2}\log T + O(1)$$

Optimal up to O(1). Beats KT (by a constant).

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## Density matrix prediction

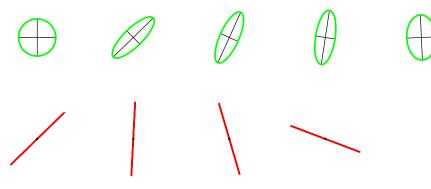
```
for trial t = 1, 2, ... do
Alg predicts with density matrix W_t
Nat reveals dyad x_t x_t^{\top}
Alg incurs loss -x_t^{\top} \log(W_t) x_t
end for
```

## Density matrix prediction

for trial t = 1, 2, ... do Alg predicts with density matrix  $W_t$ Nat reveals dyad  $x_t x_t^{\top}$ Alg incurs loss  $-x_t^{\top} \log(W_t) x_t$ end for for trial t = 1, 2, ... do Alg predicts with distr.  $\boldsymbol{\omega}_t$ Nat reveals  $\boldsymbol{x}_t \in \{\boldsymbol{e}_1, ..., \boldsymbol{e}_n\}$ Alg incurs loss  $-\log(\boldsymbol{\omega}_t^{\mathsf{T}} \boldsymbol{x}_t)$ end for

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## The outcomes: dyads

■ A dyad xx<sup>T</sup> is a rank-one matrix, where x is a vector in ℝ<sup>n</sup> of unit length.

A dyad is a classical outcome in an arbitrary orthonormal basis:

$$\boldsymbol{x} \boldsymbol{x}^{\top} = \boldsymbol{U}^{\top} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \boldsymbol{U}$$

There are continuously many dyads.

- A density matrix W is a convex combination of dyads.
  - W is a positive-semidefinite matrix of unit trace.
- A density matrix is a probability vector in an arbitrary orthonormal basis:

$$oldsymbol{W} = \sum_{i=1}^n \omega_i \, oldsymbol{a}_i oldsymbol{a}_i^ op$$



eigenvalues  $\boldsymbol{\omega}$  probability vector eigenvectors  $\boldsymbol{a}_i$  orthonormal system  $\blacksquare$  The logarithm of a density matrix  $m{W} = \sum_i \omega_i m{a}_i m{a}_i^{ op}$  is defined by

$$\log(\boldsymbol{W}) = \sum_{i} \log(\omega_i) \, \boldsymbol{a}_i \boldsymbol{a}_i^{\top}.$$

Discrepancy between prediction W and dyad  $xx^{ op}$ : matrix log loss

$$-oldsymbol{x}^ op \log(oldsymbol{W})oldsymbol{x}$$

If Alg and Nat play in the same eigensystem, i.e. x = a<sub>j</sub>, then matrix log loss becomes classical log loss:

$$-oldsymbol{x}^{ op}\log(oldsymbol{W})oldsymbol{x} \ = \ -oldsymbol{a}_j^{ op}\sum_i \log(\omega_i)oldsymbol{a}_ioldsymbol{a}_i^{ op}oldsymbol{a}_j = -\log(\omega_j) = -\log(oldsymbol{\omega}^{ op}oldsymbol{x})$$

#### ■ The Von Neumann or Quantum entropy:

$$H(\boldsymbol{A}) = -\operatorname{tr}(\boldsymbol{A} \log \boldsymbol{A})$$

equals the Shannon entropy of eigenvalues  $\alpha$  of A.

• We now compete with the empirical Von Neumann entropy:

$$\inf_{\boldsymbol{W}} \sum_{t=1}^{T} -\boldsymbol{x}_{t}^{\top} \log(\boldsymbol{W}) \boldsymbol{x}_{t} = T H (\boldsymbol{W}^{*}) \text{ where } \boldsymbol{W}^{*} = \frac{\sum_{t=1}^{T} \boldsymbol{x}_{t} \boldsymbol{x}_{t}^{\top}}{T}$$

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#### Matrix Laplace:

$$oldsymbol{W}_{t+1} \coloneqq rac{\sum_{q=1}^t oldsymbol{x}_q oldsymbol{x}_q^ op + oldsymbol{I}}{t+n}$$

Matrix Krychevsky-Trofimoff (KT):

$$\boldsymbol{W}_{t+1} \coloneqq rac{\sum_{q=1}^t \boldsymbol{x}_q \boldsymbol{x}_q^{ op} + \boldsymbol{I}/2}{t+n/2}$$

#### Matrix Laplace:

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Matrix Krychevsky-Trofimoff (KT):

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#### Theorem

Classical and matrix worst-case regrets coincide for Laplace and for KT.

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#### But why ...?

- If Alg plays Laplace or KT, then Nat will never go out-eigensystem: Any sequence of dyads not in same eigensystem is suboptimal for Nat
- The classical case is the worst case. No additional regret.
- We learn eigenvectors for free!

## Free matrix lunch for Shtarkov?

Are the classical and matrix prediction games equally hard?
Ultimate open problem: is the *classical minimax regret*

$$\min_{\boldsymbol{\omega}_1} \max_{\boldsymbol{x}_1} \cdots \min_{\boldsymbol{\omega}_T} \max_{\boldsymbol{x}_T} \sum_{t=1}^T -\log\left(\boldsymbol{\omega}_t^{\mathsf{T}} \boldsymbol{x}_t\right) - T H\left(\frac{\sum_{t=1}^T \boldsymbol{x}_t}{T}\right)$$

equal to the matrix minimax regret

$$\min_{\boldsymbol{W}_1} \max_{\boldsymbol{x}_1} \cdots \min_{\boldsymbol{W}_T} \max_{\boldsymbol{x}_T} \sum_{t=1}^T -\boldsymbol{x}_t^\top \log(\boldsymbol{W}_t) \boldsymbol{x}_t - T H\left(\frac{\sum_{t=1}^T \boldsymbol{x}_t \boldsymbol{x}_t^\top}{T}\right)$$

Is there a free matrix lunch for matrix Shtarkov?

- Only numerical evidence for this claim and intermediate conjectures.
- Regret bounds for classical and matrix Last Step Minimax coincide.

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- Matrix extensions of classical algorithms for log loss.
- Learning a matrix of  $n^2$  parameters with regret for n
- Eigenvectors are learned for free
- Classical data is worst-case

- Does the free matrix lunch hold for the matrix minimax algorithm?
- A generic method for promoting classical strategies to the matrix domain.
- Different loss functions.

## Thank you!