

Biologically-inspired algorithms and models

7. Evolutionary design

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How to represent solutions in ED (evolutionary design)?

Examples

Reasons for
the difficulty

Types

Genotype
vs. pheno-
type

References

Evolutionary design is a special case of [design automation](#).

Optimized designs can be passive (static) or active (equipped with actuators–effectors and sometimes also with sensors). One example of ED is therefore [evolutionary robotics](#).

Come up with a few genetic representations for bridge optimization.

Examples of evolutionary design (1/2)

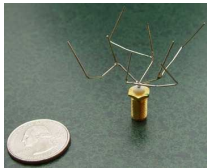
Examples

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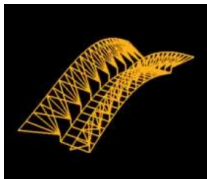
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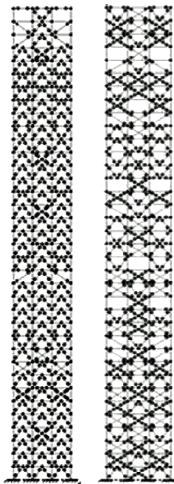
References



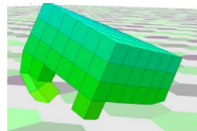
*Automated Antenna Design with
Evolutionary Algorithms,*
G. Hornby et al., 2006



*Combining Structural Analysis and
Multi-Objective Criteria for
Evolutionary Architectural Design,*
J. Byrne et al., 2011



*Evolutionary Design of
Steel Structures in Tall
Buildings,* R. Kicinger
et al., 2005



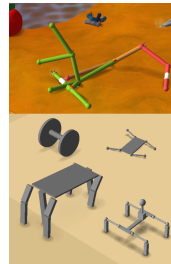
Evolving Soft Robots,
2013

*Evolutionary Develop-
mental Soft Robotics
(...) to Study Intelli-
gence and Adaptive
Behavior (...),*
F. Corucci, 2017

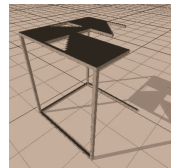
Xenobots, [Kri+20]



*Evolving virtual
creatures,*
K. Sims [Sim94]



Framsticks [KU25]



*Generative
representations,*
G. Hornby [Hor03]

Examples of evolutionary design (2/2)

Examples

Reasons for the difficulty

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Genotype vs. phenotype

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- Early evolved robots
<https://youtu.be/tgJcYx-yewA?t=237>
- Wind power plant and turbine optimization
<https://www.youtube.com/watch?v=cNaFhhwTpS8>
- Water turbine optimization (what to pay attention to, what are the goals)
<https://youtu.be/fcE6HV1g2kk?t=2477>
- Optimizing the aerodynamics of a car
https://www.youtube.com/watch?v=sw7_XWdd56c&t=25



- Optimizing the structure of a car
Czinger 21C: "Using supercomputing and AI (...) the chassis structure is generatively designed. Every component of the structure is pareto optimized for its precise function, not a single gram of material goes to waste."
<https://youtu.be/Pppne2jcgok?t=1541>

Let's compare the complexity of the classic permutation-based optimization problem and the problem of optimizing designs:

[illegible]

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Reasons for the difficulty	Property	QAP/TSP	Optimizing designs
Types	Finite set of solutions		
Genotype vs. phenotype	Discrete-continuous space		
	Genotype has constant size		
References	Obvious, natural representation		
	Simple definition of neighborhood		
	Many local optima		
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Reasons for the difficulty

Comparison of optimization difficulty

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Predictable evaluation cost		
Easy to estimate similarity		

The level of granularity in evolutionary design

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- Conceptual ED: production of high-level conceptual frameworks for designs. New design concepts can be evolved, but building blocks are provided by the designer. Example: a hydropower system as a combination of locations, dam types, tunnel lengths and modes of operation.
- Generative ED: generation of the form of design directly. No pre-defined high-level concepts, no conventions, no imposed knowledge ([the Einstellung effect](#)). Low-level building blocks defined. Complex representations. Examples: tables, heatsinks, optical prisms, aerodynamic and hydrodynamic forms, bridges, cranes, [EHW](#), analogue circuits.

The Einstellung effect and human vs. natural design

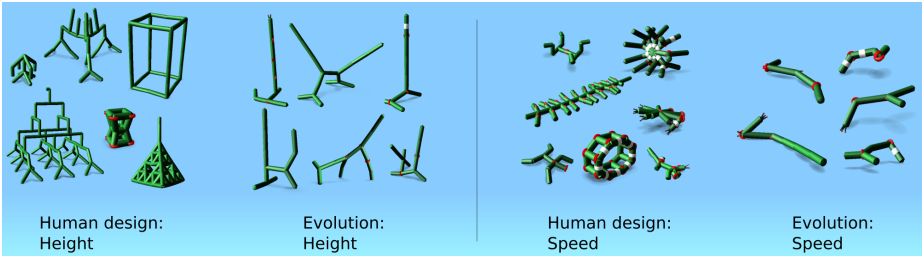
From 7th Int. Conf. on Swarm Intelligence, session on Morphogenetic Engineering:

Engineered products:

- often made of a number of unique, heterogeneous components assembled in a precise and complicated way,
- work deterministically following the specifications given by the designers.

By contrast (compare the figure below), self-organization in natural systems (physical, biological, ecological, social):

- often relies on the repetition of identical agents and stochastic dynamics,
- nontrivial behavior can emerge from relatively simple rules,
- however, most natural patterns can be described with a small number of statistical variables,
- such patterns are random or shaped by boundary conditions, but never exhibit an intrinsic architecture like engineered products do.



Embryogeny in ED

Examples

Reasons for the difficulty

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Genotype vs. phenotype

References

In evolutionary design, phenotypes are usually much more different from their genotypic representations, than in typical optimization problems. That means that mapping from genotype to phenotype (“embryogeny”) is needed and may be complex – we talked about it when discussing evolutionary programming.

The goal is good **scalability** (the ability to scale up and create more sophisticated designs [[Hor08](#)]) and **evolvability** (the ability to produce offspring that are diverse/more fit [[Gaj+19](#)]) – consider the example of optimizing a *toothbrush* [discussion].

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The same desirable properties of the genotype-phenotype mapping that we identified in the toothbrush example also apply when optimizing bridges, turbines, robots, cars, etc.

The genotype–phenotype mapping: nature vs. ED

Examples

Reasons for the difficulty

Types

Genotype vs. phenotype

References

In nature embryogeny is defined by interactions between genes, their phenotypic effects and the environment in which the embryo develops. There are chains of interacting “rules”; the flow of activation is not completely predetermined and preprogrammed; it is dynamic, parallel and adaptive.*

In optimization (e.g., in evolutionary design) embryogenies can be [Ben99]:

- External (non-evolved). Fixed, static rules, which specify how phenotypes are constructed from the genotypes. E.g. *f0*, *f1*, *fH*, *f7* and *f9* in Framsticks [KU21].

*<https://nautil.us/the-strange-inevitability-of-evolution-235189/>

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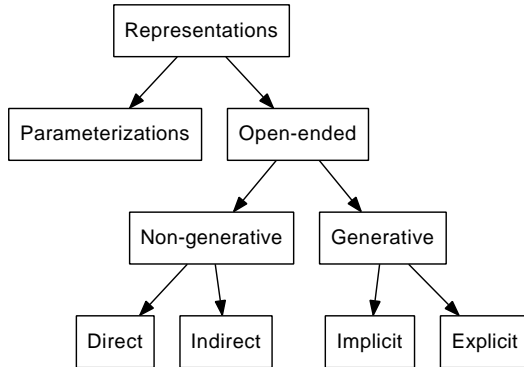
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- Implicit (evolved). The same genes can be activated and suppressed many times; the same genes can specify *different* functions. Conditional iteration, subroutines, parallel interpretation of genes are allowed. However, it is very difficult to design a good implicit representation. E.g. *fB*, *f6* and *fL* in Framsticks.

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The genotype–phenotype mapping: classification

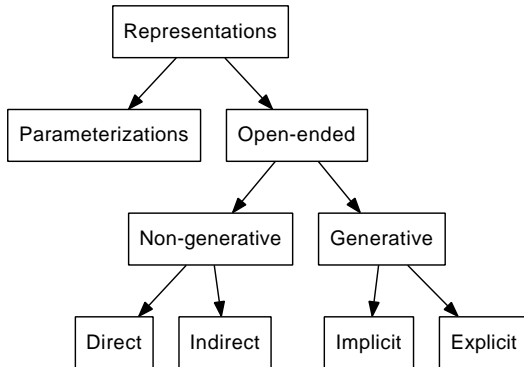
Another, similar classification of embryogenies [Hor03]:



In non-generative representations, each gene is activated once. In Direct and Explicit, the meaning of genes is fixed (not subject to evolution).

The genotype–phenotype mapping: classification

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Question: to which category belongs: permutation in TSP, DNA in nature, *f9* in ED?

Automated development of the genotype–phenotype mapping

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The development of an efficient embryogeny/mapping may be itself posed as an optimization or machine learning problem (“find an encoding that results in a smooth fitness landscape: maximize FDC” or “find an encoding that makes similar phenotypes genetic neighbors”).

Such a problem may be addressed using techniques similar to word embeddings* or (neural) autoencoders** [KKM21].

*https://en.wikipedia.org/wiki/Word_embedding

**<https://en.wikipedia.org/wiki/Autoencoder>

References I

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References

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References II

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References

[Sim94]

Karl Sims. “Evolving virtual creatures”. In: *Proceedings of the 21st annual conference on Computer graphics and interactive techniques*. ACM. 1994, pp. 15–22. URL: <https://www.cs.drexel.edu/~david/Classes/Papers/p15-sims.pdf>.