1 Notation

 $\mathbf{t} \in [1,T]$ - time step/number of iterations/examples/minibatches

 ${\bf d}\,$ - dimensionality of the parameters vector

 $\epsilon\,$ - small constant for numerical stability

 $\Theta_t \in \mathbb{R}^d$ - parameter vector at time **t**, of dimensionality **d**

 $L_t(\Theta)$ - loss function at time t (e.g. different minibatch in each timestep)

 $\eta \in (0,1]$ - learning rate, step size

 $\nabla\,$ - $\mathbf{nabla},$ not delta

 \odot - a dot in a circle, elementwise product (Hadamard product)

 $g_t = \nabla L_t(\Theta_t \, \text{ - gradient in time } \mathbf{t}$

 $g_t^2 = g_t \odot g_t$ - 'notation abuse'

 $\rho \in [0,1); \mu \in [0,1)\,$ - some coefficients

initialization - assume initialization with zeros unless stated otherwise

2 SGD

Stadnard formulation

$$\Theta_{t+1} = \Theta_t - \eta \nabla L_t(\Theta_t) \tag{1}$$

Ordinary Momentum

$$v_{t+1} = \mu v_t - \eta \nabla L_t(\Theta_t); \mu \in [0, 1)$$

$$\Theta_{t+1} = \Theta_t + v_{t+1}$$
(2)

Nesterov Accelerated Gradient (NAG)

$$v_{t+1} = \mu v_t - \eta \nabla L_t(\Theta_t + \mu v_t); \mu \in [0, 1)$$

$$\Theta_{t+1} = \Theta_t + v_{t+1}$$

$$(3)$$

3 Dimension-wise Adaptive Methods

Θ

Adagrad[1]

$$G_t = \sum_{i=1}^t g_t^2 \tag{4}$$
$$_{t+1} = \Theta_t - \frac{\eta}{\sqrt{G_t + \epsilon}} \odot g_t$$

RMSProp[2]

$$G_{t} = 0.9 * G_{t-1} + 0.1 * g_{t}^{2} = 0.1 \sum_{i=1}^{t} 0.9^{T-i} g_{t}^{2}$$

$$\Theta_{t+1} = \Theta_{t} - \frac{\eta}{\sqrt{G_{t} + \epsilon}} \odot g_{t}$$
(5)

Adadelta[3]

$$G_{t} = \rho G_{t-1} + (1-\rho)g_{t}^{2} = (1-\rho)\sum_{i=1}^{t} \rho^{t-i}g_{t}^{2}$$

$$\overline{\Delta}_{t-1} = \rho \overline{\Delta}_{t-2} + (1-\rho)\Delta\Theta_{t-1}^{2}$$

$$\Delta\Theta_{t} = \frac{\sqrt{\overline{\Delta}_{t-1} + \epsilon}}{\sqrt{G_{t} + \epsilon}} \odot g_{t}$$

$$\Theta_{t+1} = \Theta_{t} + \Delta\Theta_{t}$$

$$(6)$$

3.1 Worth reading perhaps

- Adam[4]
- vSGD maybe [5]
- CoCob [6]
- a blogpost about momentum

References

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- [4] Diederik P. Kingma and Jimmy Ba. Adam: A method for stochastic optimization. CoRR, abs/1412.6980, 2014.
- [5] Tom Schaul, Sixin Zhang, and Yann LeCun. No more pesky learning rates. In Sanjoy Dasgupta and David McAllester, editors, *Proceedings of the 30th International Conference on Machine Learning*, volume 28 of *Proceedings of Machine Learning Research*, pages 343–351, Atlanta, Georgia, USA, 17–19 Jun 2013. PMLR.
- [6] Francesco Orabona and Tatiana Tommasi. Backprop without learning rates through coin betting. *CoRR*, abs/1705.07795, 2017.